

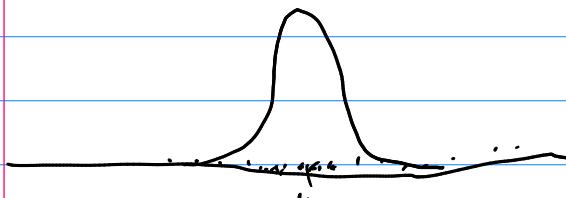
Robustness

- Model Misspecification
- Measurement error
- Dirty data
- Adversary

Simple example:

$$X_1, \dots, X_n \sim N(\mu, 1)$$

Goal: Est μ from X_1, \dots, X_n



$$\hat{\mu} = \frac{1}{n} \sum X_i. \text{ If } n \text{ is large enough, } \hat{\mu} \approx \mu.$$

Adversary: Can add pts to dataset (few)

If \bullet is very large ($> 100n + \mu$) then $|\hat{\mu} - \mu|$ will be large (> 100)

Defenses:

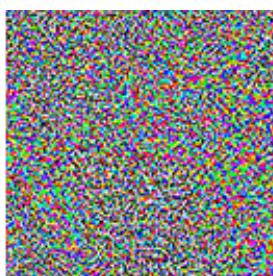
- Prune dataset
- Median, instead of mean

Today: Robustness to adversarial Examples



"panda"
57.7% confidence

$$+ \epsilon$$



$$=$$



"gibbon"
99.3% confidence

Carefully
Crafted

Setting: Model trained on some training data.

At test time, adversary can modify each point "a bit"

Adversary goal: Reduce test accuracy as much as possible

x' is an adversarial example for x on model f_θ if

1. (Informal) $x \approx x' \Leftrightarrow d(x, x')$ is small $\Leftrightarrow x$ and x' have same label according to human
2. $f_\theta(x) \neq f_\theta(x')$

Proxy for "human perception" in 1:

- Use dist instead

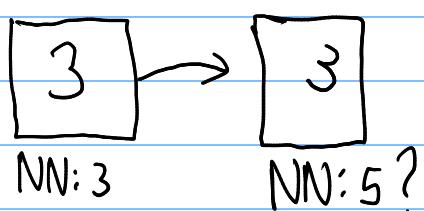
Common: l_p dist $(\|x - x'\|_p = \left(\sum (x_i - x'_i)^p \right)^{1/p})$

Adversary may output x' in $\{y : \|x - y\|_p \leq \varepsilon\}$

Common: $p=0, 2, \infty \leftarrow$ Today: Can change each pixel by \uparrow small $\leq \varepsilon$.
Can change ε pts arbitrarily

Other dists

- Wasserstein
- Translations, Rotations, Resizing



Attacker:

Given trained model f_θ , test example x .

Construct x' :

$$1. \|x - x'\|_\infty \leq \varepsilon$$

$$2. f_\theta(x) \neq f_\theta(x')$$

Notes:

a) White-box

b) Untargeted vs Targeted attacks $\left(f_\theta(x') = c \neq f_\theta(x), \text{ for target } c \right)$

Optimize NN:

$$\min_{\theta} \frac{1}{n} \sum l(x_i, y_i, \theta)$$

Data fixed, optimize θ

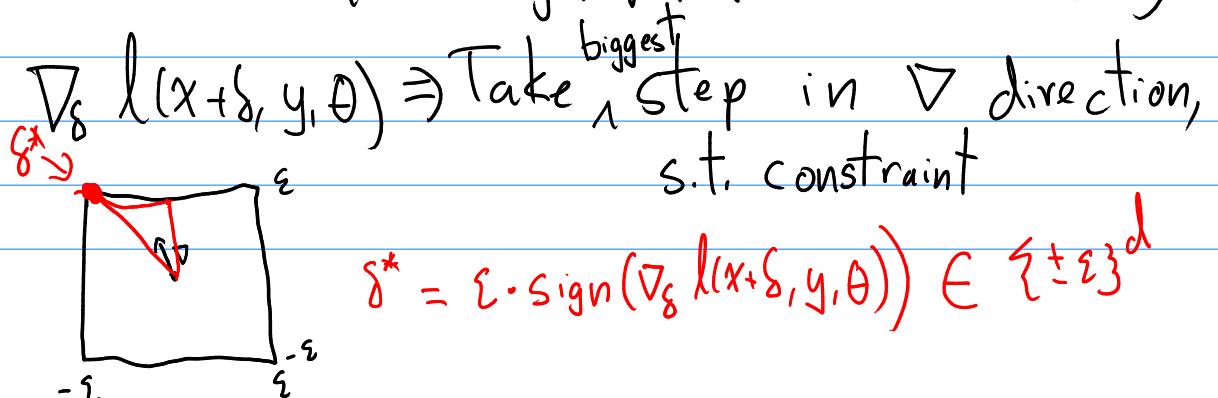
$$\theta \leftarrow \theta - \eta \frac{1}{n} \sum \nabla_{\theta} l(x_i, y_i, \theta)$$

Generate Adversarial example

$$s' = \arg \max_{s \in \mathbb{R}^d} l(x + s, y, \theta) \text{ s.t. } \|s\|_\infty \leq \varepsilon. \Rightarrow x' = x + s'$$

Gradient-Based opt

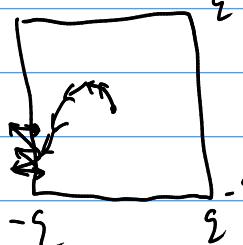
- Simple: Fast Gradient Sign Method (FGSM)



Better: Projected Gradient Descent (PGD)

$$\delta^{t+1} = \text{Proj} \left(\delta^t + \eta \text{Sign} (\nabla_{\delta} l(x+\delta^t, y, \theta)) \right)$$

↑ Same as before, but η is hyper param
 Projects into $[-\varepsilon, \varepsilon]^d$ if necessary



$$\text{Proj}([3\varepsilon, -2\varepsilon, 0.5\varepsilon])$$

$$= [\varepsilon, -\varepsilon, 0.5\varepsilon]$$

Untargeted: $\max_{\delta} l(x+\delta, y, \theta) \text{ s.t. } \|\delta\|_\infty \leq \varepsilon$

Targeted to c : $\max_{\delta} l(x+\delta, y, \theta) - l(x+\delta, c, \theta) \text{ s.t. } \|\delta\|_\infty \leq \varepsilon$

Defenses

Adversarial Training

- Usual goal: $\min_{\theta} \mathbb{E}_{(x,y) \sim P} [l(x, y, \theta)]$

- Robust setting: $\min_{\theta} \mathbb{E}_{(x,y) \sim P} \left[\max_{\delta: \|\delta\|_\infty \leq \varepsilon} l(x+\delta, y, \theta) \right]$

$$\hookrightarrow \min_{\theta} \frac{1}{n} \sum_i \max_{\delta_i: \|\delta_i\|_\infty \leq \varepsilon} l(x_i + \delta_i, y_i, \theta)$$

How to solve

1. Draw minibatch B

2. For each (x_i, y_i) in B , compute $\delta_i^* = \underset{\delta_i: \|\delta_i\|_\infty \leq \varepsilon}{\operatorname{argmax}} l(x_i + \delta_i, y_i, \theta)$

3. $\theta \leftarrow \theta - \eta \frac{1}{|B|} \sum_{i \in B} \nabla_{\theta} l(x_i + \delta_i^*, y_i, \theta)$ (use methods above)

4. Repeat

- Athalye, Carlini, Wagner '18

- ICLR '18 accepted 9 papers on adv defns.

Defense	Dataset	Distance	Accuracy
Buckman et al. (2018)	CIFAR	0.031 (ℓ_∞)	0%*
Ma et al. (2018)	CIFAR	0.031 (ℓ_∞)	5%
Guo et al. (2018)	ImageNet	0.005 (ℓ_2)	0%*
Dhillon et al. (2018)	CIFAR	0.031 (ℓ_∞)	0%
Xie et al. (2018)	ImageNet	0.031 (ℓ_∞)	0%*
Song et al. (2018)	CIFAR	0.031 (ℓ_∞)	9%*
Samangouei et al. (2018)	MNIST	0.005 (ℓ_2)	55%**
Madry et al. (2018)	CIFAR	0.031 (ℓ_∞)	47%
Na et al. (2018)	CIFAR	0.015 (ℓ_∞)	15%

Backdoor attacks

