

Lec 19: Generative Adversarial Networks

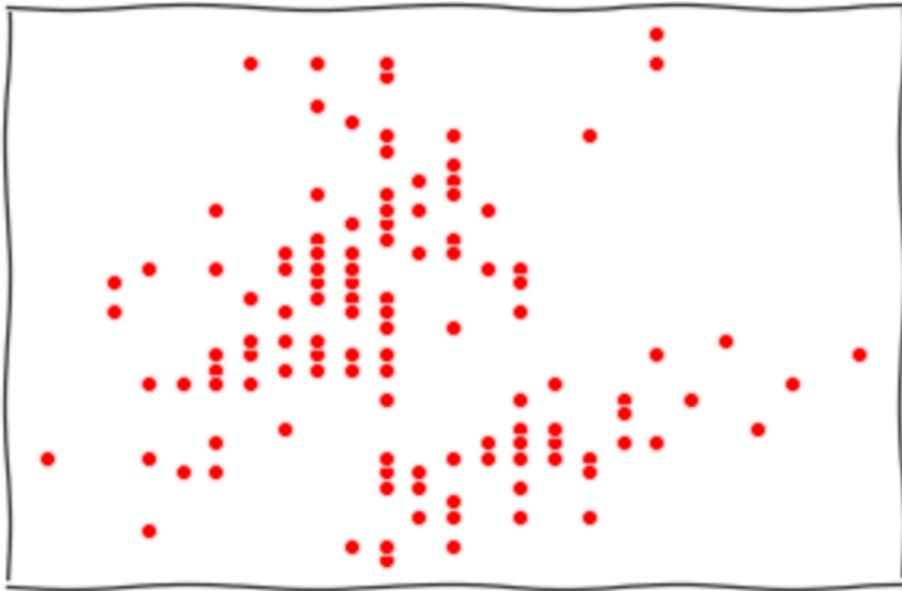
Yaoliang Yu

July 14, 2020



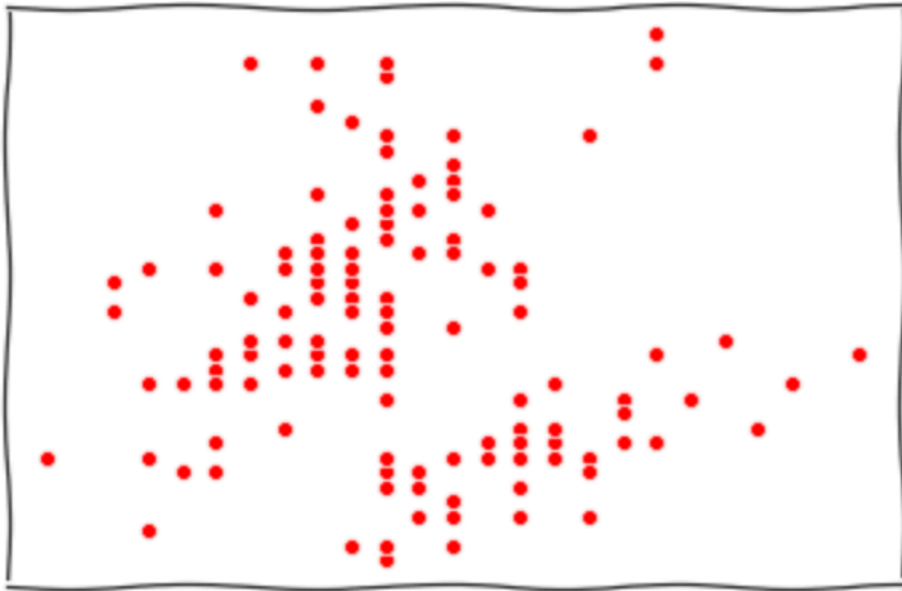
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density estimation

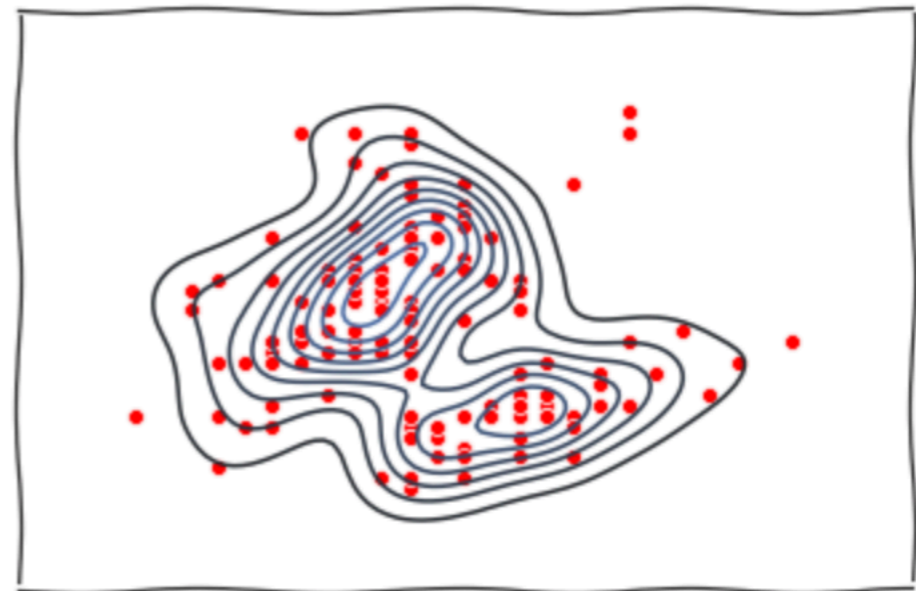


$$\mathbf{data} = \{\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_n\}$$

density estimation



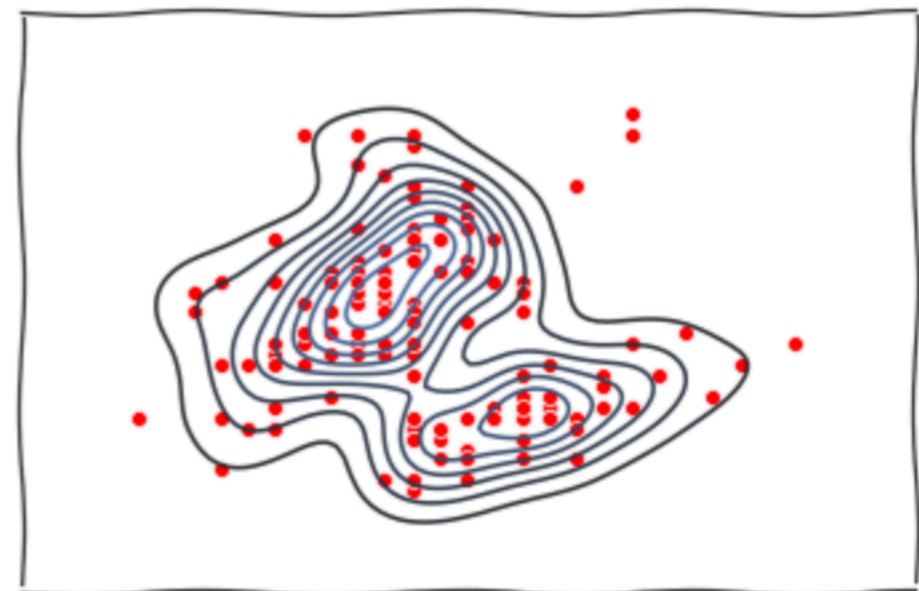
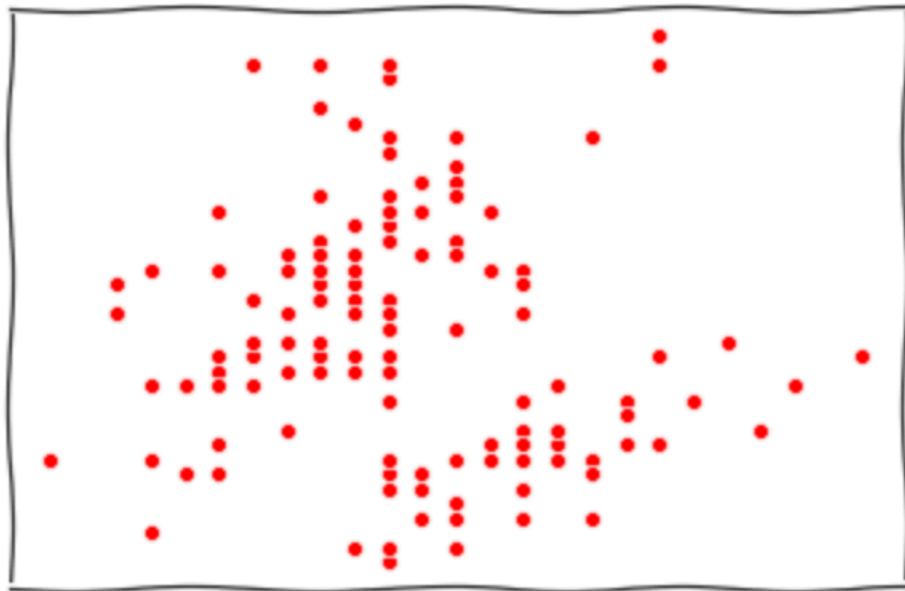
data = $\{\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_n\}$



estimate $p(\mathbf{x})$

If we can generate, then we can classify

Review: Maximum Likelihood



data = $\{\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_n\}$

estimate $p(\mathbf{x})$

$$\min_{\theta} \text{KL}(p(\mathbf{x}) \parallel q_{\theta}(\mathbf{x})) \equiv \int -\log q_{\theta}(\mathbf{x}) \cdot p(\mathbf{x}) d\mathbf{x} \approx -\frac{1}{n} \sum_{i=1}^n \log q_{\theta}(\mathbf{x}_i)$$

“distance”

unknown truth

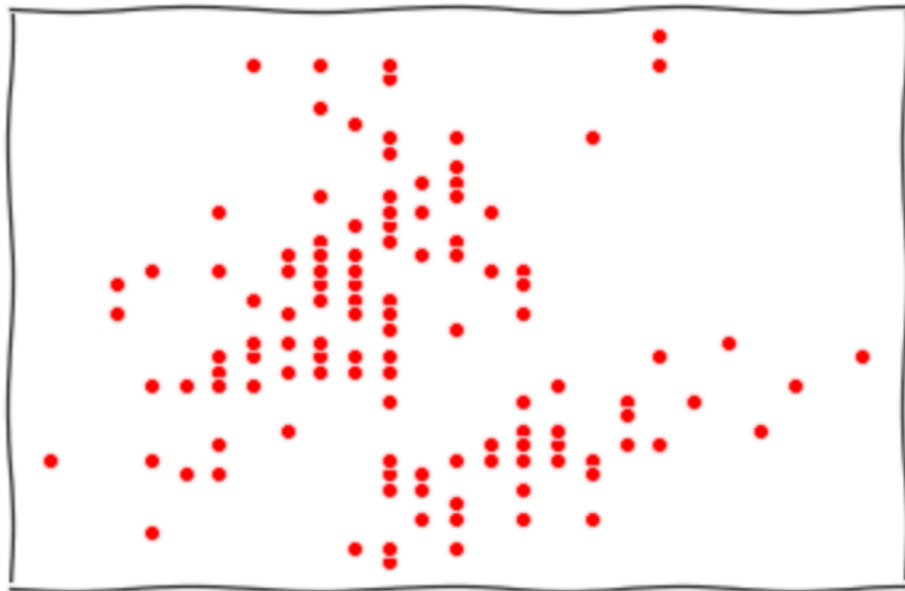
model

likelihood

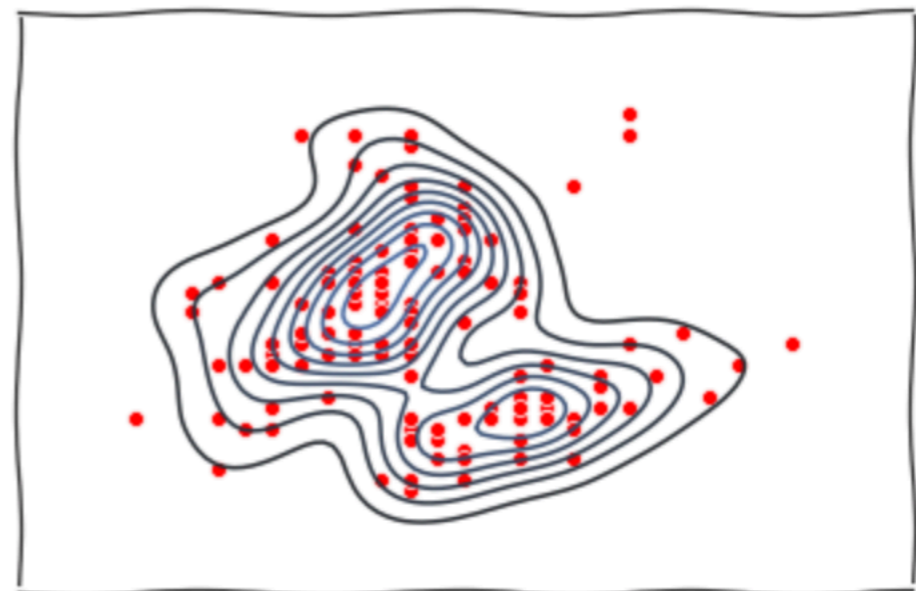
0 iff $q=p$

explicitly evaluating $q_{\theta}(\mathbf{x})$

Preview: Generative Adversarial Network



data = $\{\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_n\}$

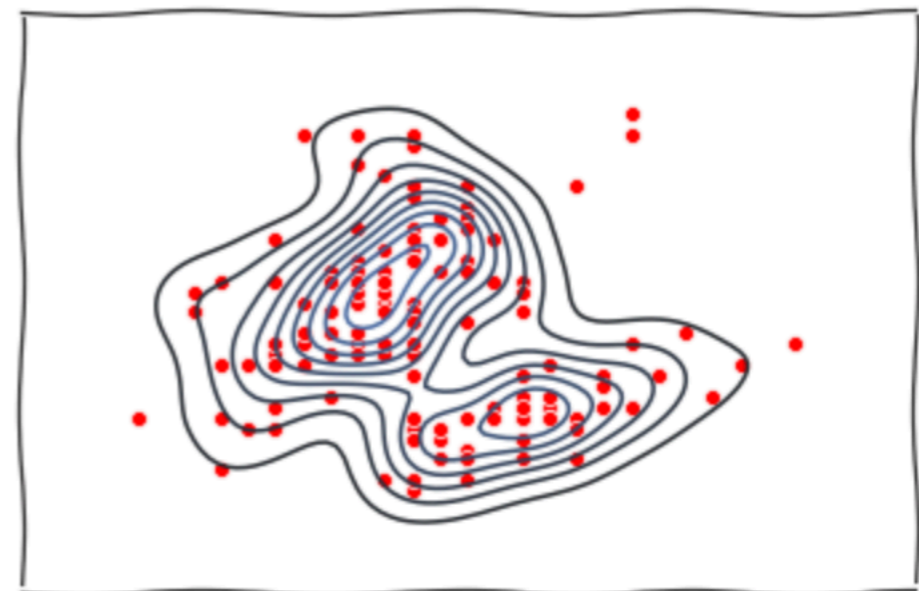
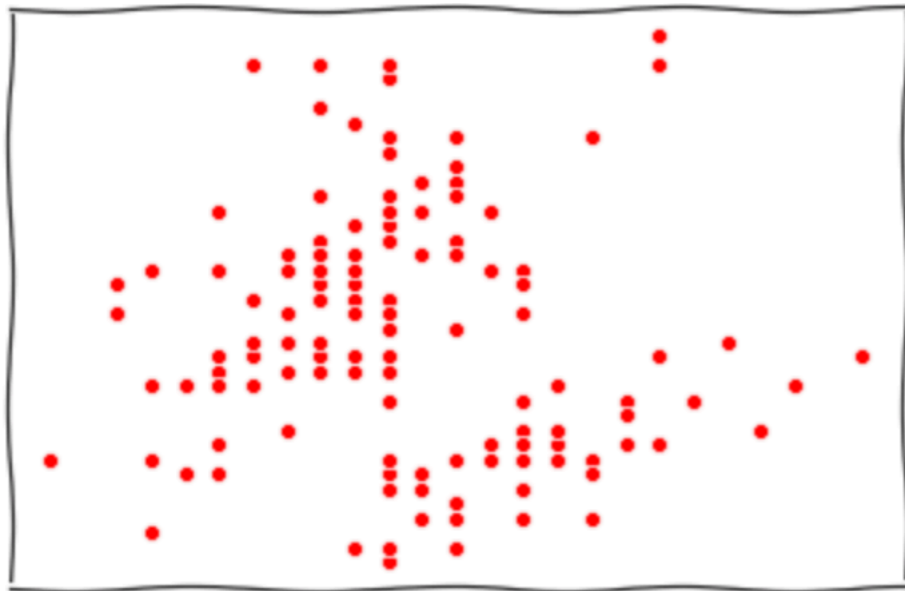


estimate $q(\mathbf{x})$

$$\min_{\theta} \text{KL}(p(\mathbf{x}) \| q_{\theta}(\mathbf{x})) \equiv \int -\log q_{\theta}(\mathbf{x}) \cdot p(\mathbf{x}) d\mathbf{x} \approx -\frac{1}{n} \sum_{i=1}^n \log q_{\theta}(\mathbf{x}_i)$$

explicitly **sampling** **evaluating** $q_{\theta}(\mathbf{x})$

Preview: Generative Adversarial Network



data = $\{\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_n\}$

estimate $p(\mathbf{x})$

$$\min_{\theta} \text{KL}(p(\mathbf{x}) \| q_{\theta}(\mathbf{x})) \equiv \int -\log q_{\theta}(\mathbf{x}) \cdot p(\mathbf{x}) d\mathbf{x} \approx -\frac{1}{n} \sum_{i=1}^n \log q_{\theta}(\mathbf{x}_i)$$

||

discriminator

$$\max_{S \in \mathcal{S} \subseteq \mathbb{R}^d} \int S(\mathbf{x}) \cdot p(\mathbf{x}) d\mathbf{x} - \int f^*(S(\mathbf{x})) \cdot q_{\theta}(\mathbf{x}) d\mathbf{x}$$

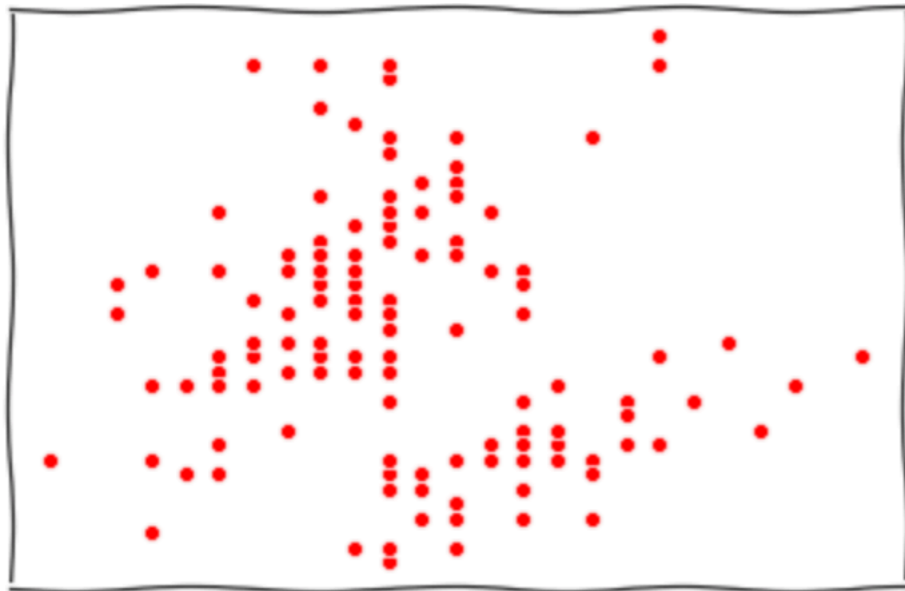
≈

generator

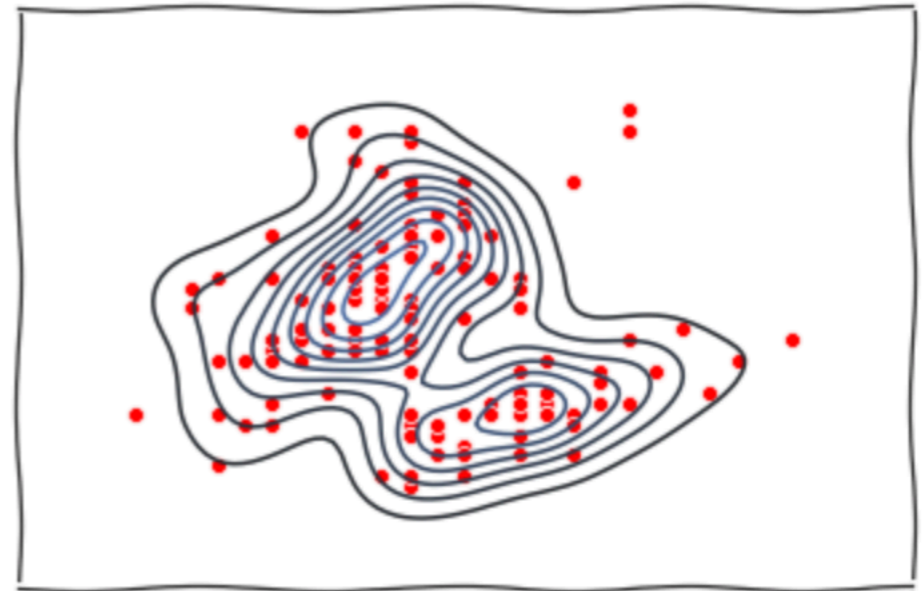
$$\min_T \max_S \frac{1}{n} \sum_{i=1}^n S(\mathbf{x}_i) - \frac{1}{m} \sum_{j=1}^m f^*(S(T(\mathbf{z}_j)))$$

explicitly **sampling** **evaluating** $q_{\theta}(\mathbf{x})$

Review: Expectation-Maximization



data = $\{\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_n\}$



estimate $p(\mathbf{x})$

$$\min_{\theta} \min_{p(\mathbf{z}|\mathbf{x})} \text{KL}\left(p(\mathbf{x}, \mathbf{z}) \| q_{\theta}(\mathbf{x}, \mathbf{z})\right) \approx \frac{1}{n} \sum_{i=1}^n \int [\log p(\mathbf{z} | \mathbf{x}_i) - \log q_{\theta}(\mathbf{x}_i, \mathbf{z})] p(\mathbf{z} | \mathbf{x}_i) d\mathbf{z}$$

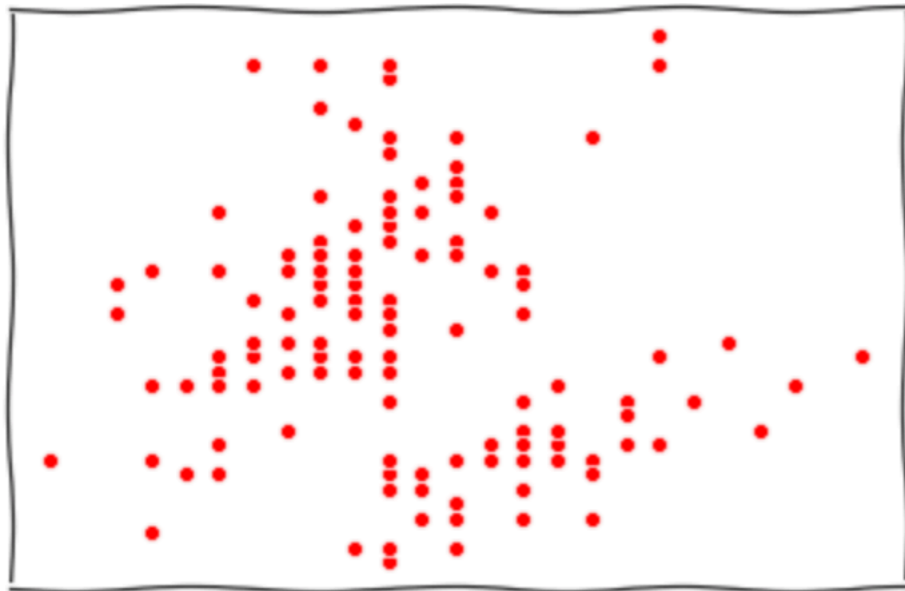
E-step: $p(\mathbf{z} | \mathbf{x}) = q_{\theta}(\mathbf{z} | \mathbf{x})$

explicitly evaluating $q_{\theta}(\mathbf{z} | \mathbf{x})$

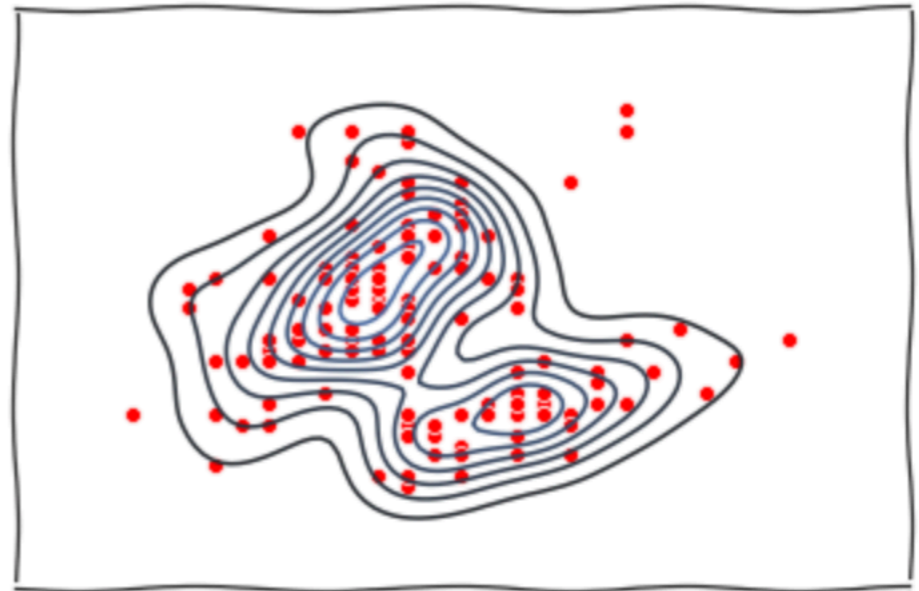
M-step: $\min_{\theta} -\frac{1}{n} \sum_{i=1}^n \int \log q_{\theta}(\mathbf{x}_i, \mathbf{z}) \cdot p(\mathbf{z} | \mathbf{x}_i) d\mathbf{z}$

explicitly evaluating $q_{\theta}(\mathbf{x}, \mathbf{z})$

Monte Carlo EM



data = $\{\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_n\}$



estimate $p(\mathbf{x})$

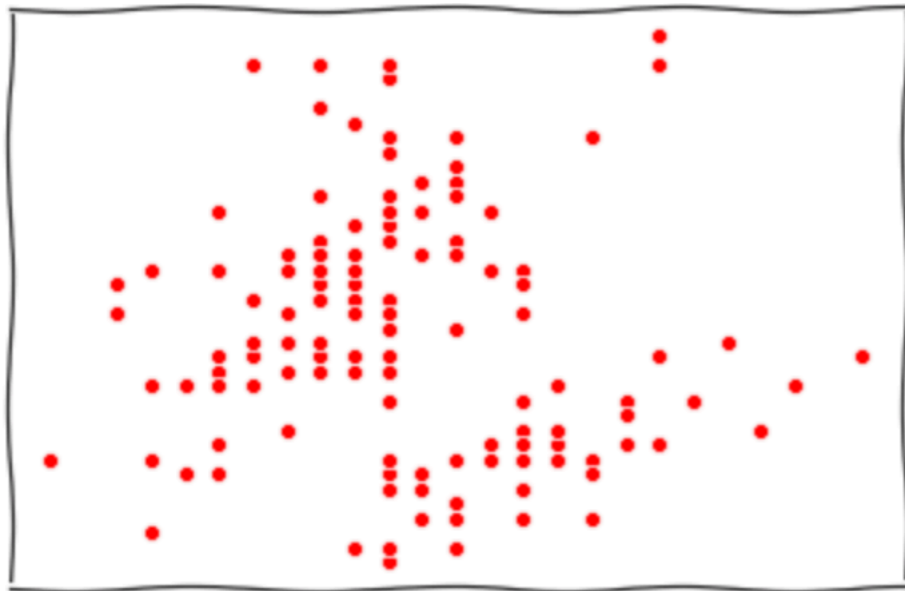
$$\min_{\theta} \min_{p(\mathbf{z}|\mathbf{x})} \text{KL}\left(p(\mathbf{x}, \mathbf{z}) \parallel q_{\theta}(\mathbf{x}, \mathbf{z})\right) \approx \frac{1}{n} \sum_{i=1}^n \int [\log p(\mathbf{z} | \mathbf{x}_i) - \log q_{\theta}(\mathbf{x}_i, \mathbf{z})] p(\mathbf{z} | \mathbf{x}_i) d\mathbf{z}$$

E-step: $p(\mathbf{z} | \mathbf{x}) = q_{\theta}(\mathbf{z} | \mathbf{x})$ sampling
explicitly evaluating $q_{\theta}(\mathbf{z} | \mathbf{x})$

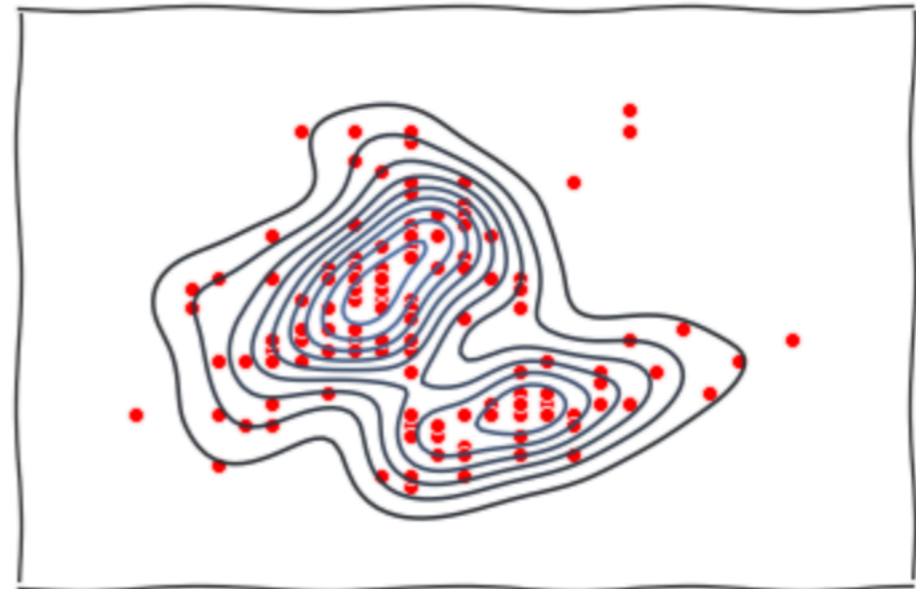
$$\mathbf{M}\text{-step: } \min_{\theta} -\frac{1}{n} \sum_{i=1}^n \int \log q_{\theta}(\mathbf{x}_i, \mathbf{z}) \cdot p(\mathbf{z} | \mathbf{x}_i) d\mathbf{z} \approx -\frac{1}{n} \sum_{i=1}^n \sum_{j=1}^m \log q_{\theta}(\mathbf{x}_i, \mathbf{z}_j)$$

explicitly evaluating $q_{\theta}(\mathbf{x}, \mathbf{z})$

Preview: Variational Auto-Encoder



data = $\{\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_n\}$



estimate $p(\mathbf{x})$

$$\min_{q_{\theta}(\mathbf{x}|\mathbf{z})} \min_{p_{\varphi}(\mathbf{z}|\mathbf{x})} \text{KL}\left(p(\mathbf{x})p_{\varphi}(\mathbf{z}|\mathbf{x})\|q_{\theta}(\mathbf{x}|\mathbf{z})q(\mathbf{z})\right)$$

unknown truth

encoder

decoder

fixed normal

explicitly evaluating $q_{\theta}(\mathbf{x}|\mathbf{z})$

explicitly evaluating $p_{\varphi}(\mathbf{z}|\mathbf{x})$

Applications

Image Super-Resolution

bicubic
(21.59dB/0.6423)



SRResNet
(23.53dB/0.7832)



SRGAN
(21.15dB/0.6868)

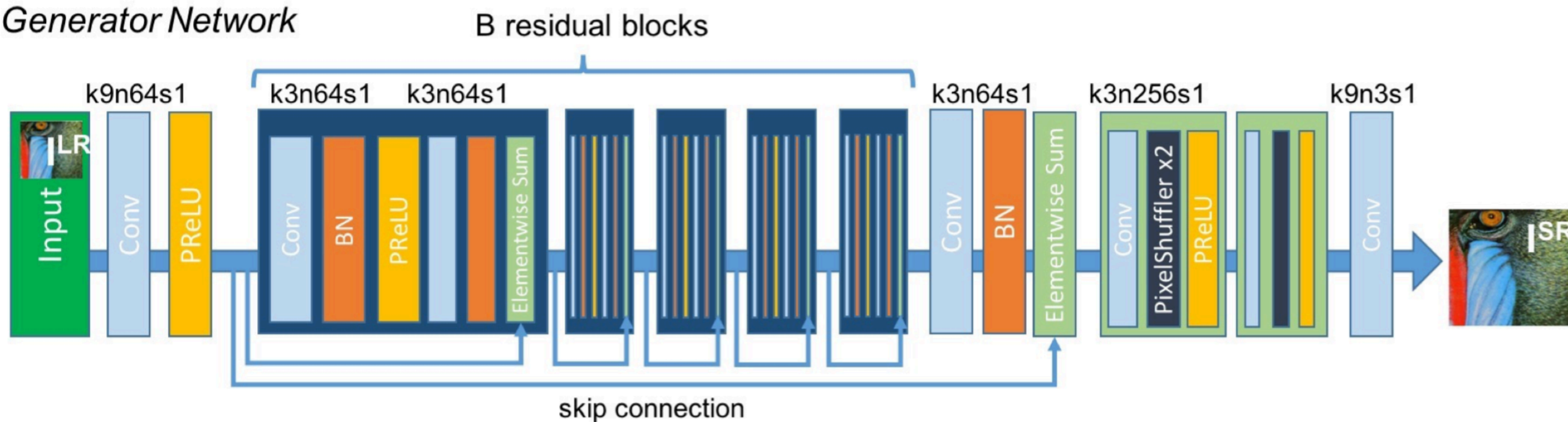


original

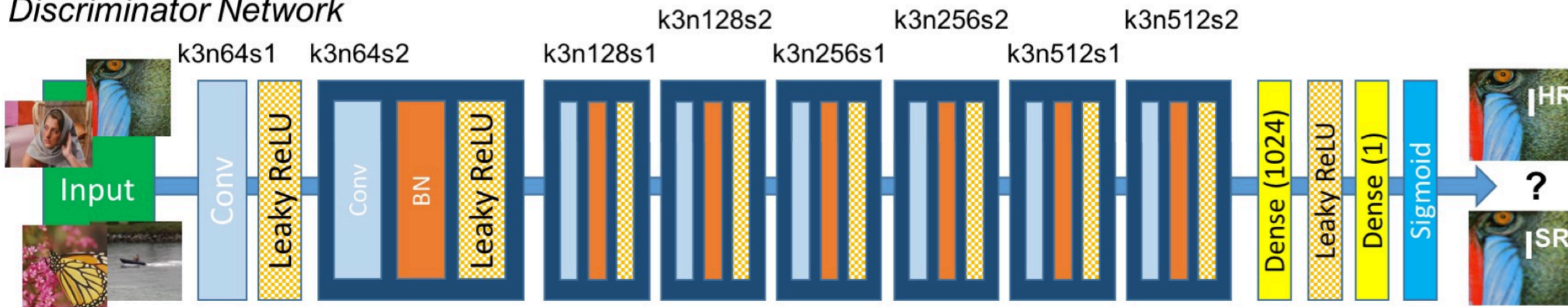


Image Super-Resolution

Generator Network



Discriminator Network



Interactive Image Generation



Neural photo editing

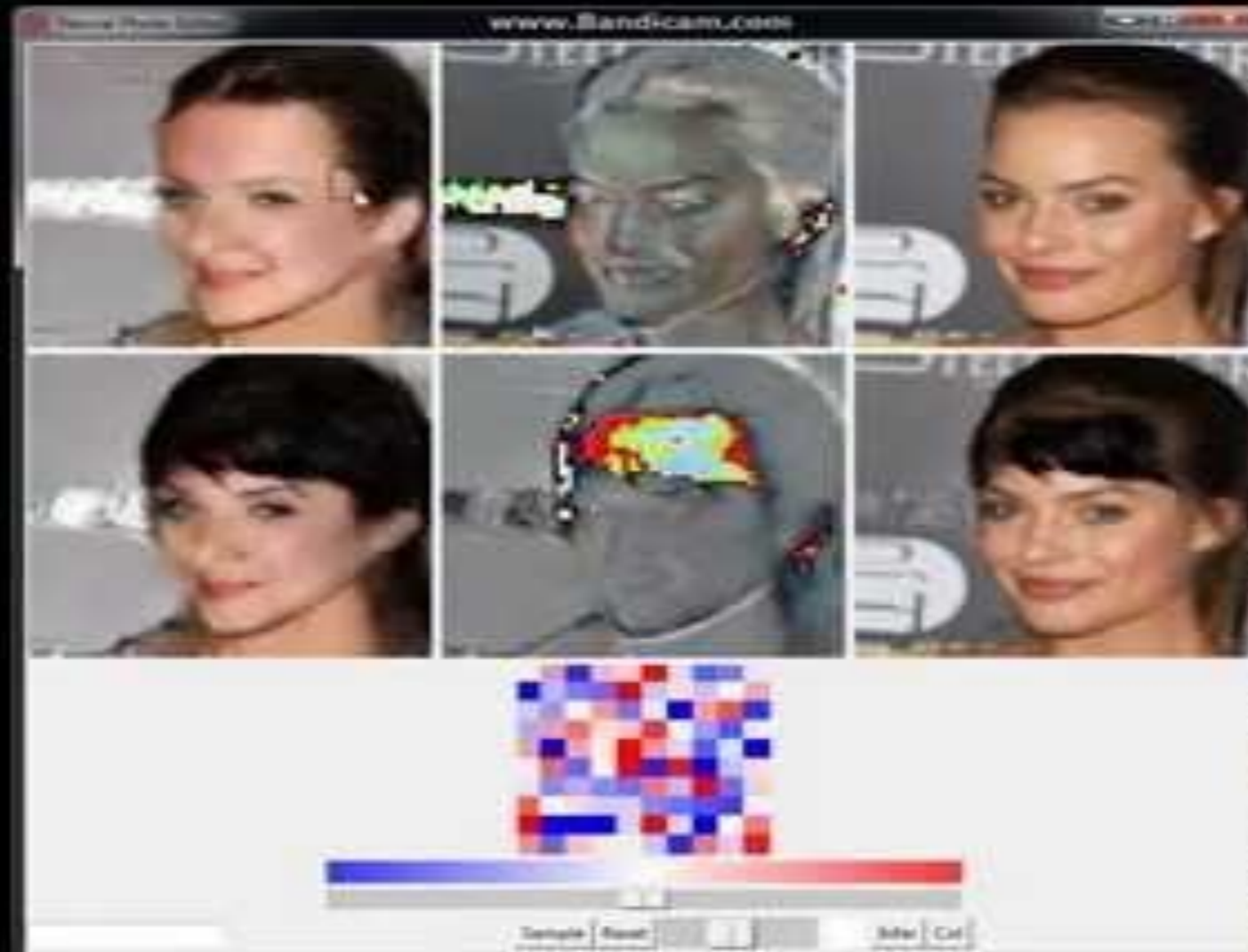
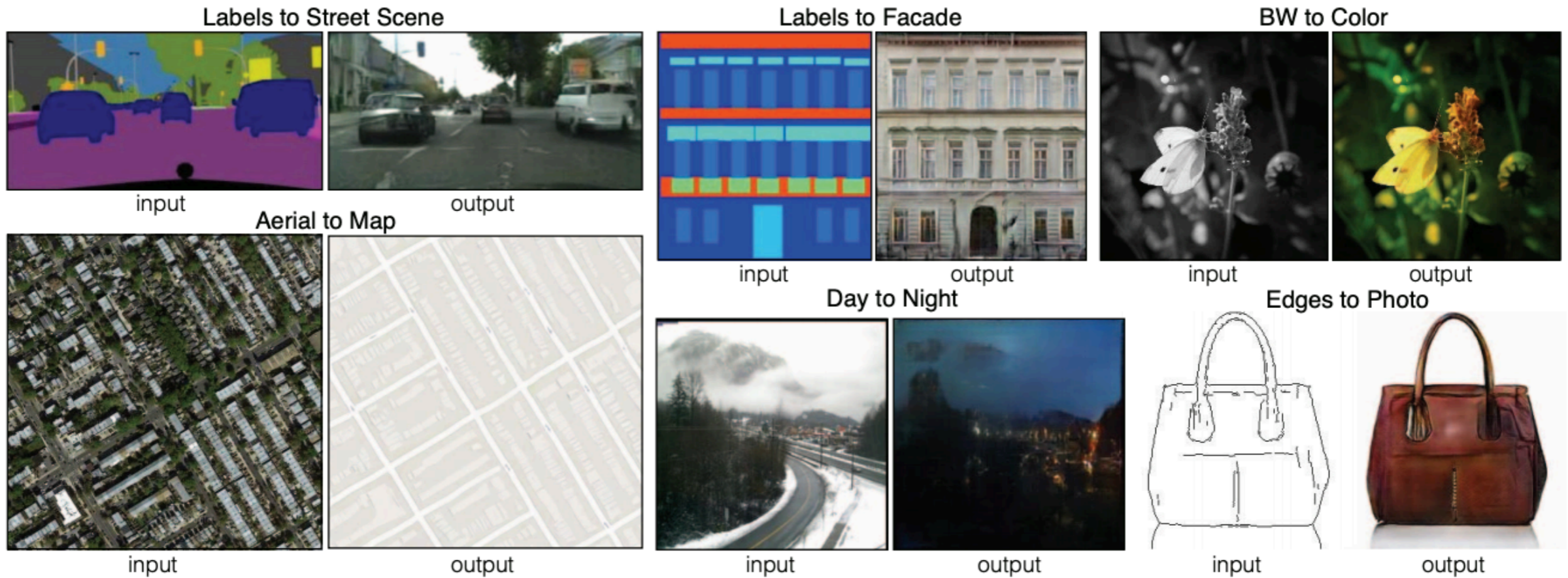
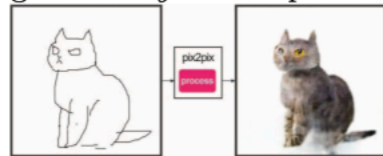


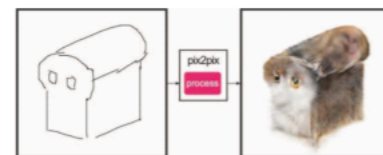
Image to Image Translation



#edges2cats by Christopher Hesse



by @gods_tail



by @ivymyt



by @yvid

Sketch → Portrait



by Mario Klingemann

“Do as I do”



by Brannon Dorsey

Depth → Streetview



by Jasper van Loenen

Palette generation



by Jack Qiao

Background removal

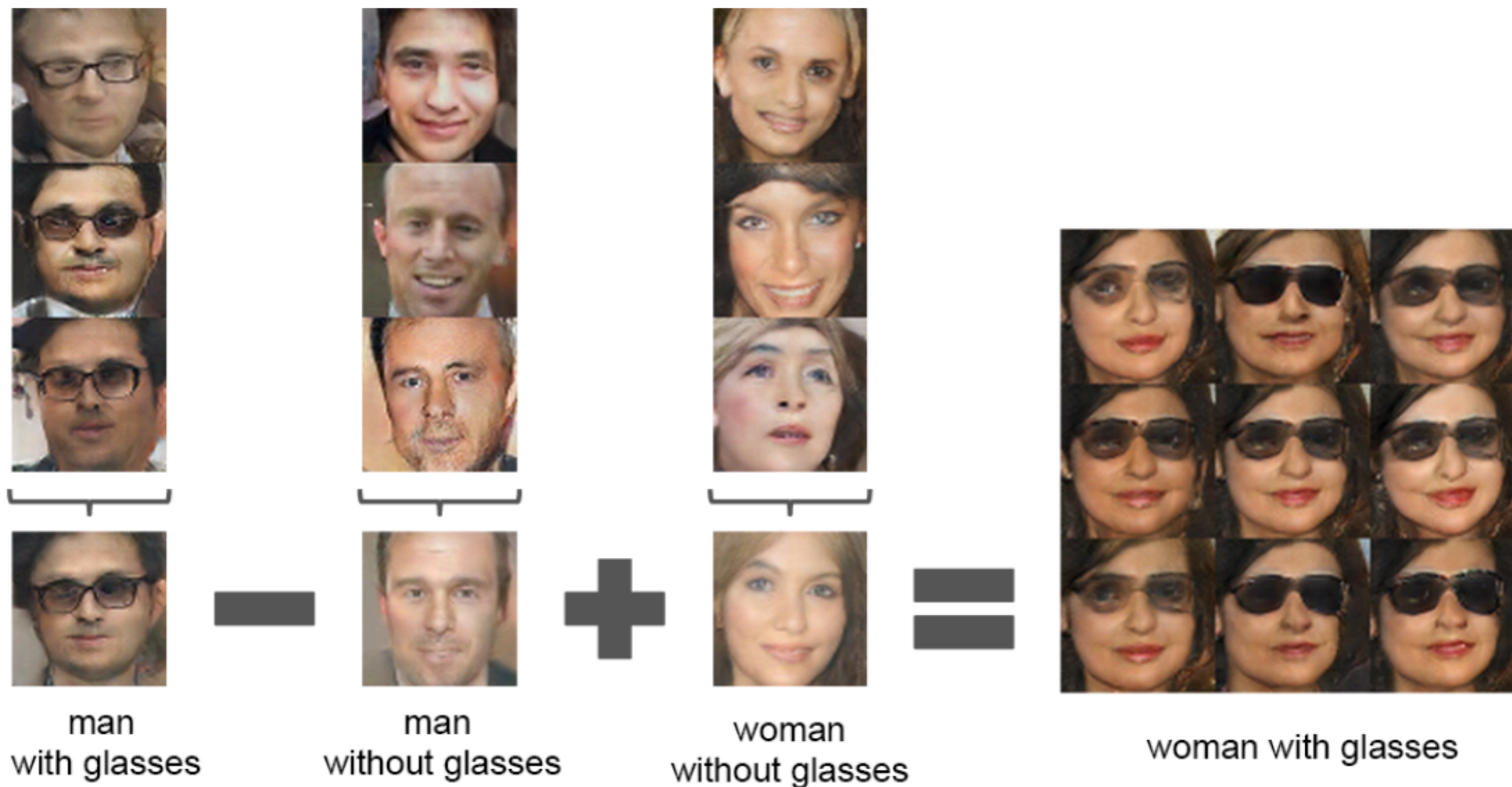


by Kaihu Chen

Sketch → Pokemon



by Bertrand Gondouin





Context (human-written): In a shocking finding, scientist discovered a herd of unicorns living in a remote, previously unexplored valley, in the Andes Mountains. Even more surprising to the researchers was the fact that the unicorns spoke perfect English.

GPT-2: The scientist named the population, after their distinctive horn, Ovid’s Unicorn. These four-horned, silver-white unicorns were previously unknown to science.

Now, after almost two centuries, the mystery of what sparked this odd phenomenon is finally solved.

Dr. Jorge Pérez, an evolutionary biologist from the University of La Paz, and several companions, were exploring the Andes Mountains when they found a small valley, with no other animals or humans. Pérez noticed that the valley had what appeared to be a natural fountain, surrounded by two peaks of rock and silver snow.

Pérez and the others then ventured further into the valley. “By the time we reached the top of one peak, the water looked blue, with some crystals on top,” said Pérez.

Pérez and his friends were astonished to see the unicorn herd. These creatures could be seen from the air without having to move too much to see them – they were so close they could touch their horns.

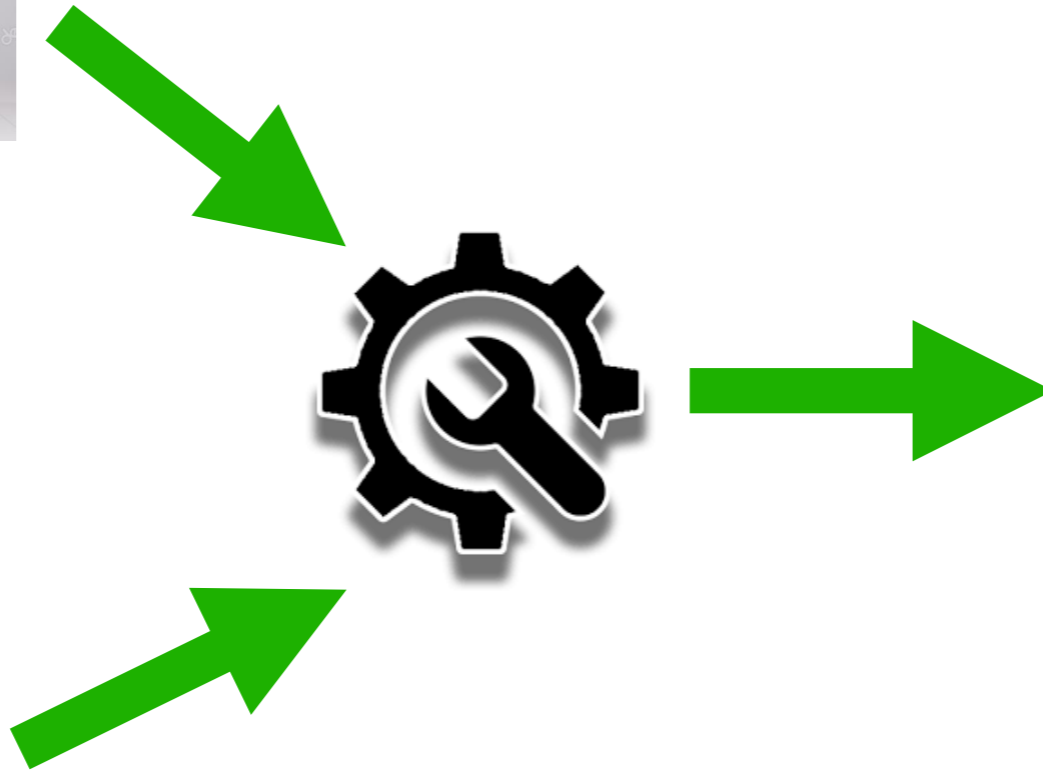
While examining these bizarre creatures the scientists discovered that the creatures also spoke some fairly regular English. Pérez stated, “We can see, for example, that they have a common ‘language,’ something like a dialect or dialectic.”

Dr. Pérez believes that the unicorns may have originated in Argentina, where the animals were believed to be descendants of a lost race of people who lived there before the arrival of humans in those parts of South America.

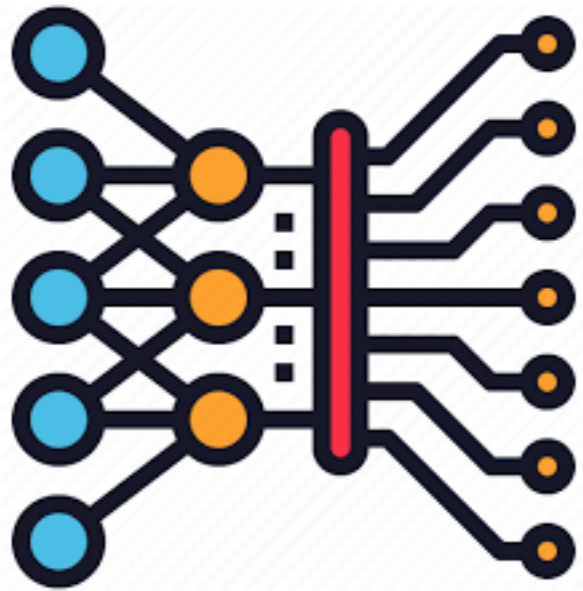
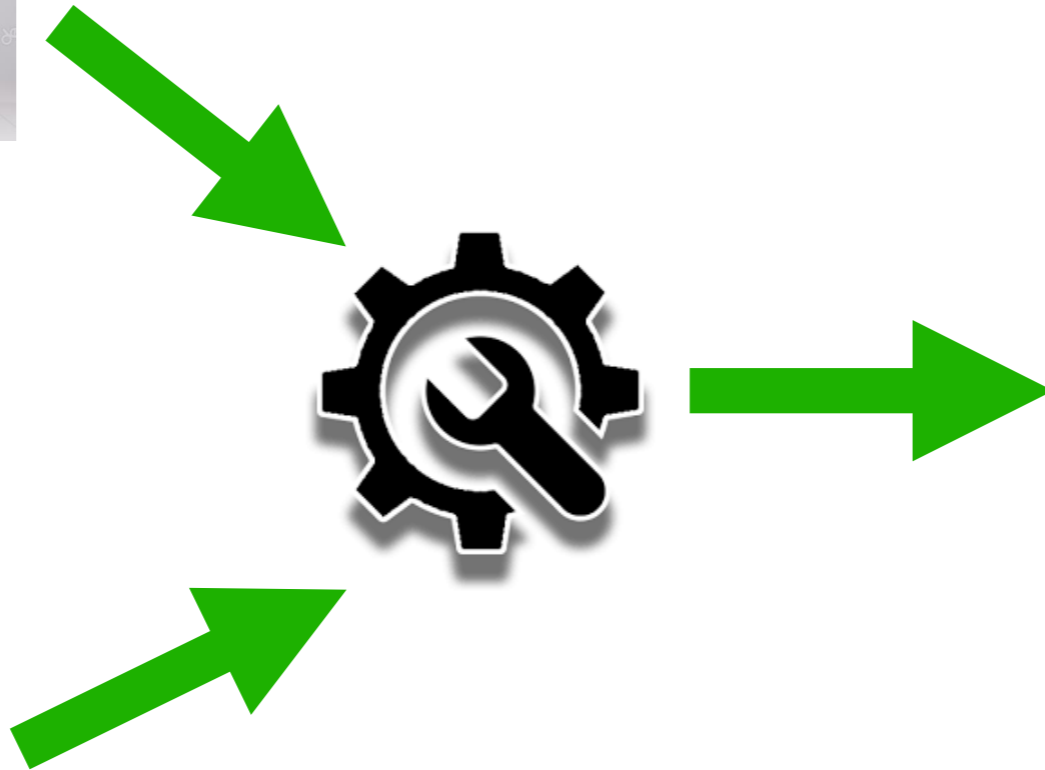
While their origins are still unclear, some believe that perhaps the creatures were created when a human and a unicorn met each other in a time before human civilization. According to Pérez, “In South America, such incidents seem to be quite common.”

However, Pérez also pointed out that it is likely that the only way of knowing for sure if unicorns are indeed the descendants of a lost alien race is through DNA. “But they seem to be able to communicate in English quite well, which I believe is a sign of evolution, or at least a change in social organization,” said the scientist.

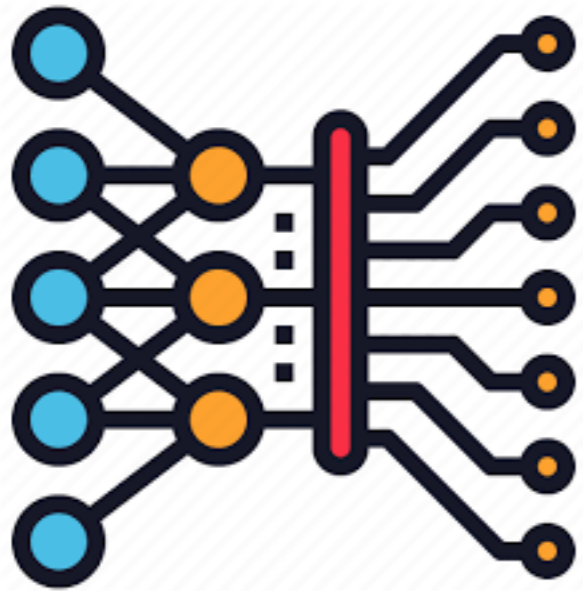
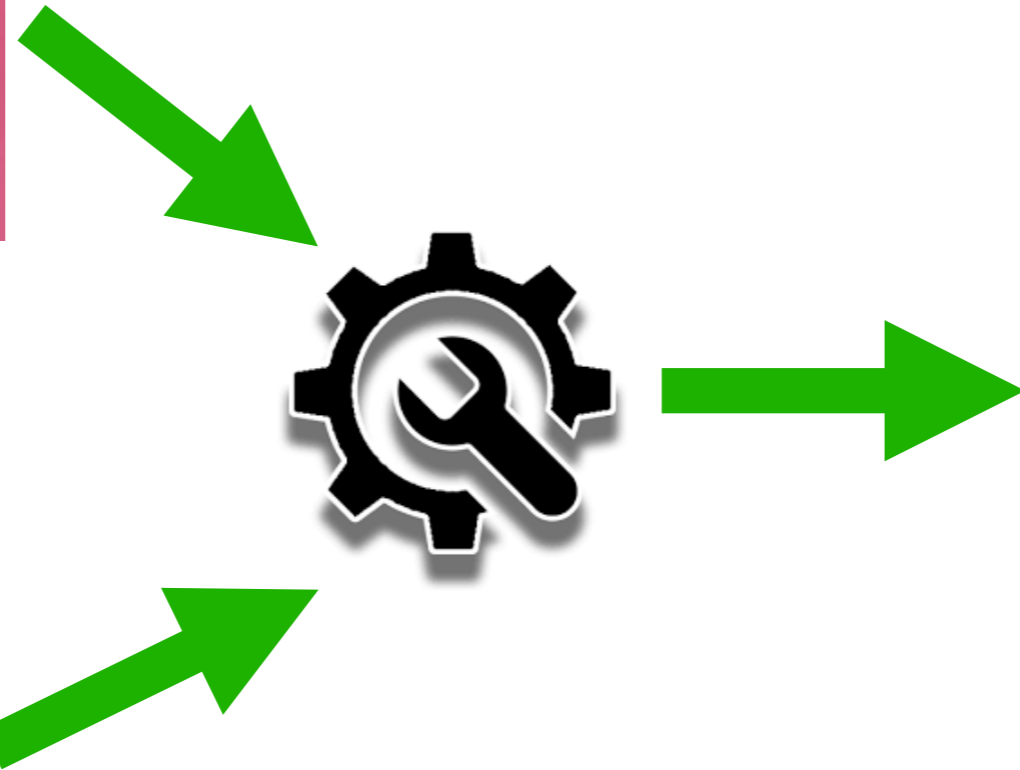
Generative Training?



Generative Training?

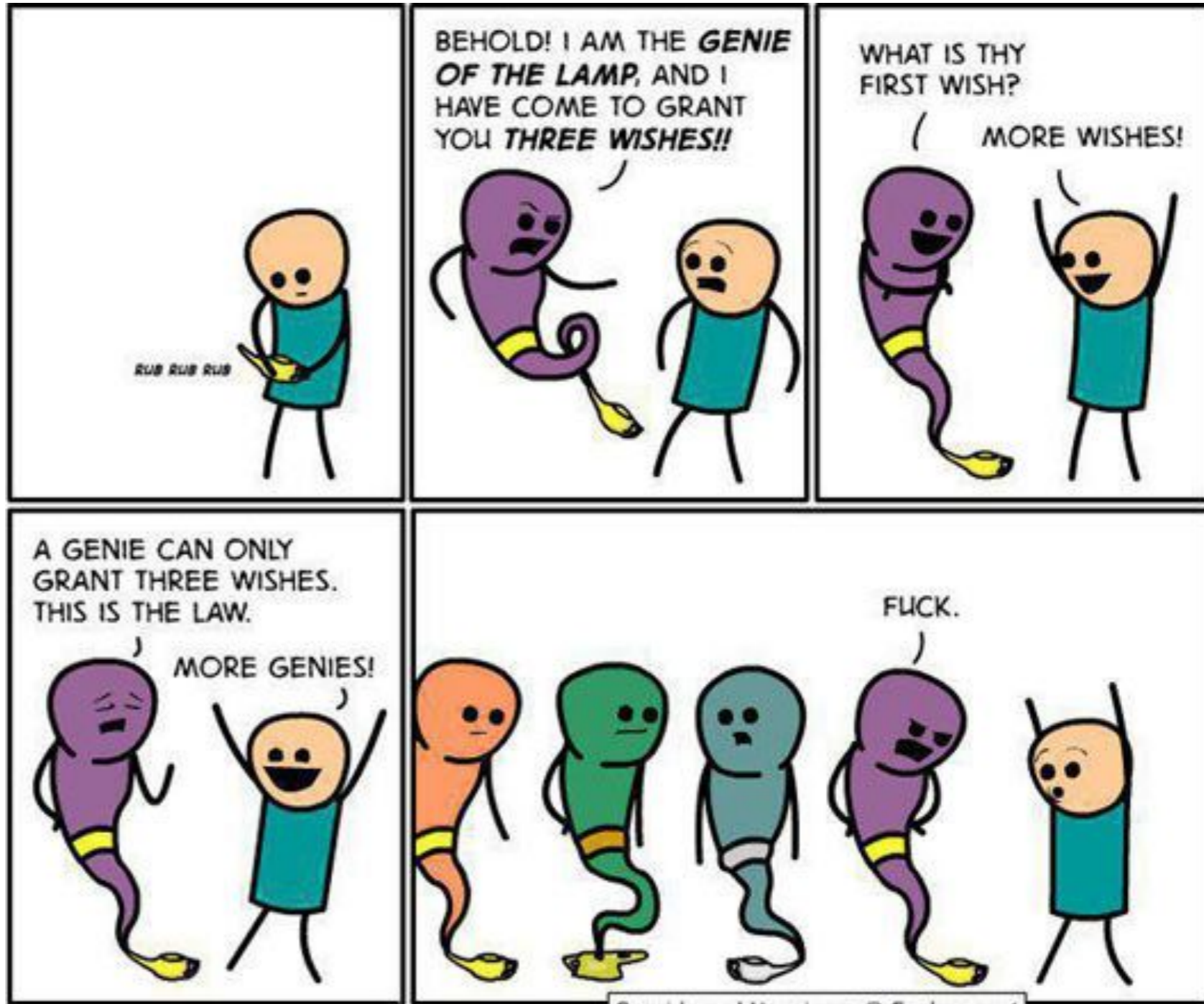


Generative Training?



Charles Ponzi
(1882-1949)

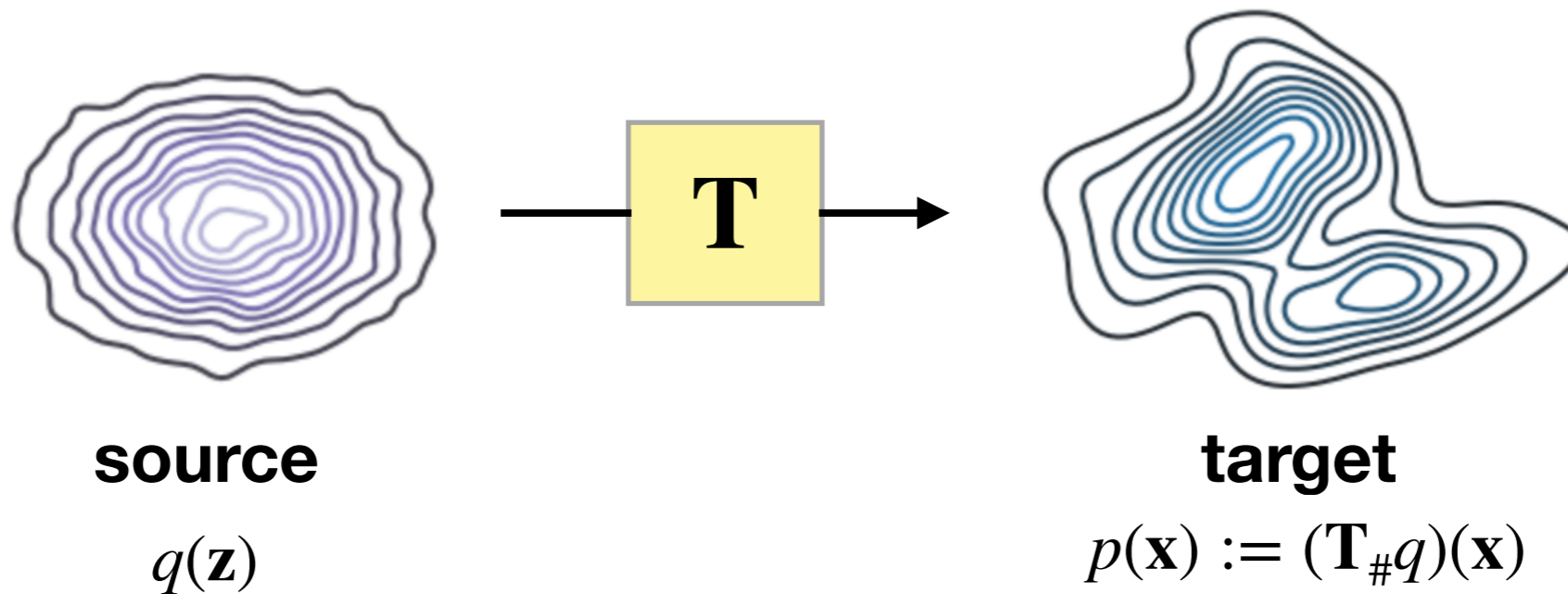
Generative Training?



Cyanide and Happiness © Explosm.net

A simple trick

Push-forward

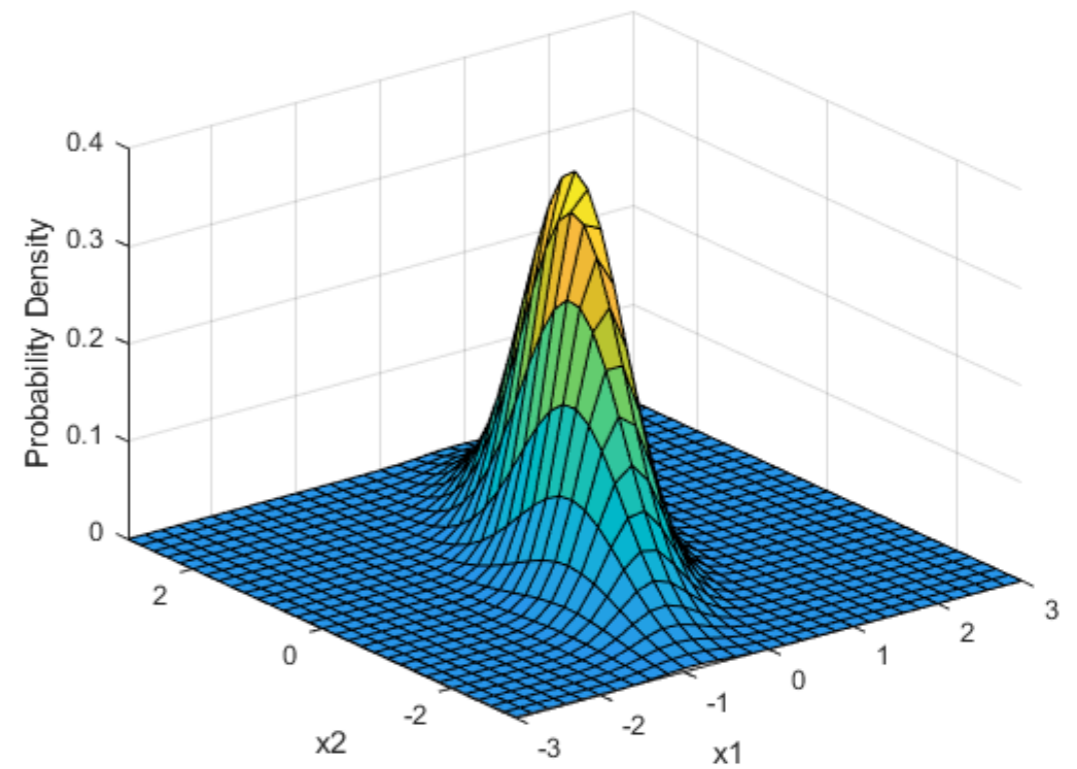
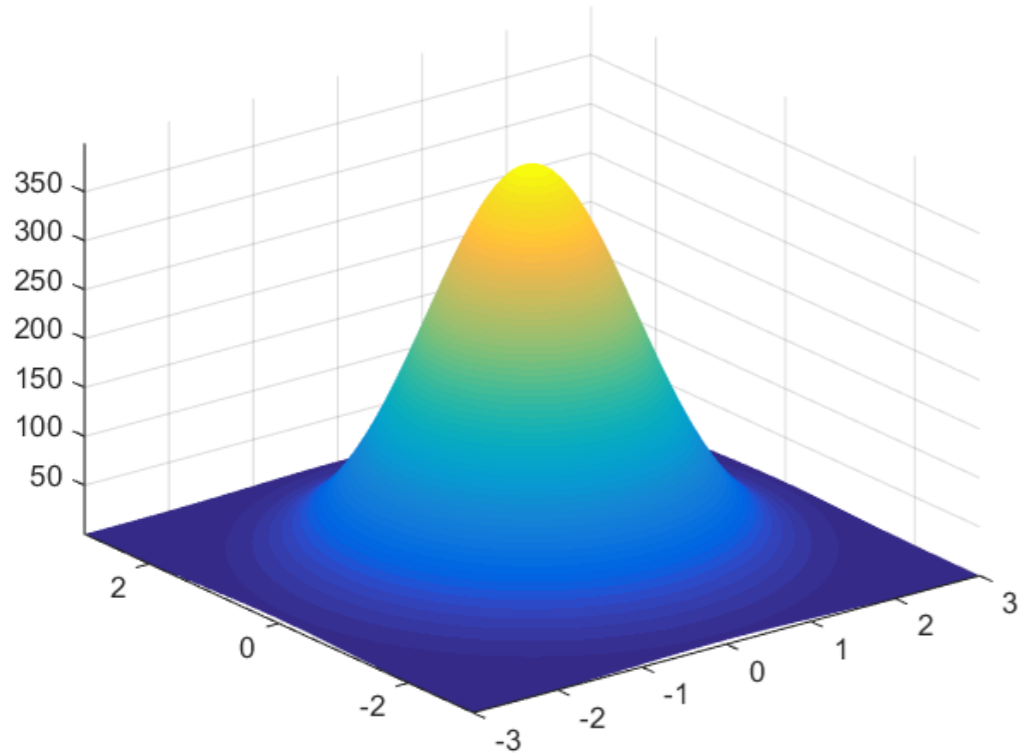


change-of-variable formula: $p(\mathbf{x}) = q(\mathbf{T}^{-1}(\mathbf{x})) \cdot \left| \nabla \mathbf{T}(\mathbf{T}^{-1}(\mathbf{x})) \right|^{-1}$

to sample \mathbf{x} from $p(\mathbf{x})$: sample \mathbf{z} from q , then set $\mathbf{x} = \mathbf{T}(\mathbf{z})$

parameterize \mathbf{T} through a deep network: $\mathbf{T}(\mathbf{x}) = \text{DNN}(\mathbf{x}; \mathbf{w})$

Linear Example



$$TT^T = \Sigma$$

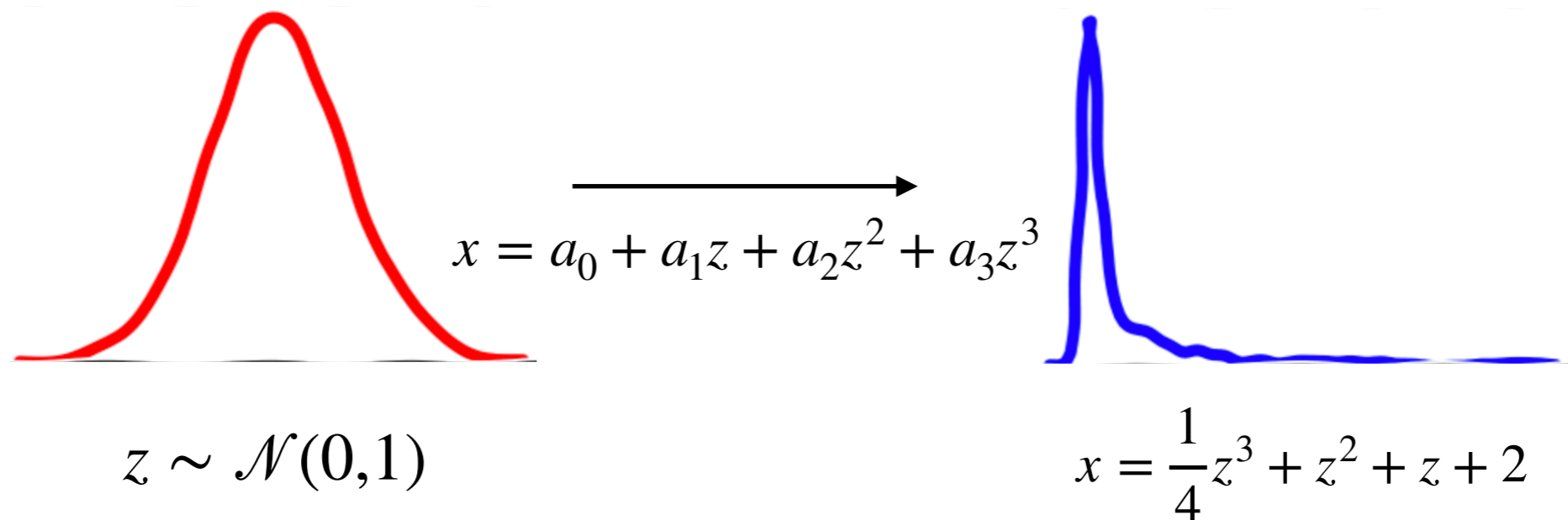
$$Z \sim \mathcal{N}(0, I)$$



$$TZ =: X \sim \mathcal{N}(0, \Sigma)$$

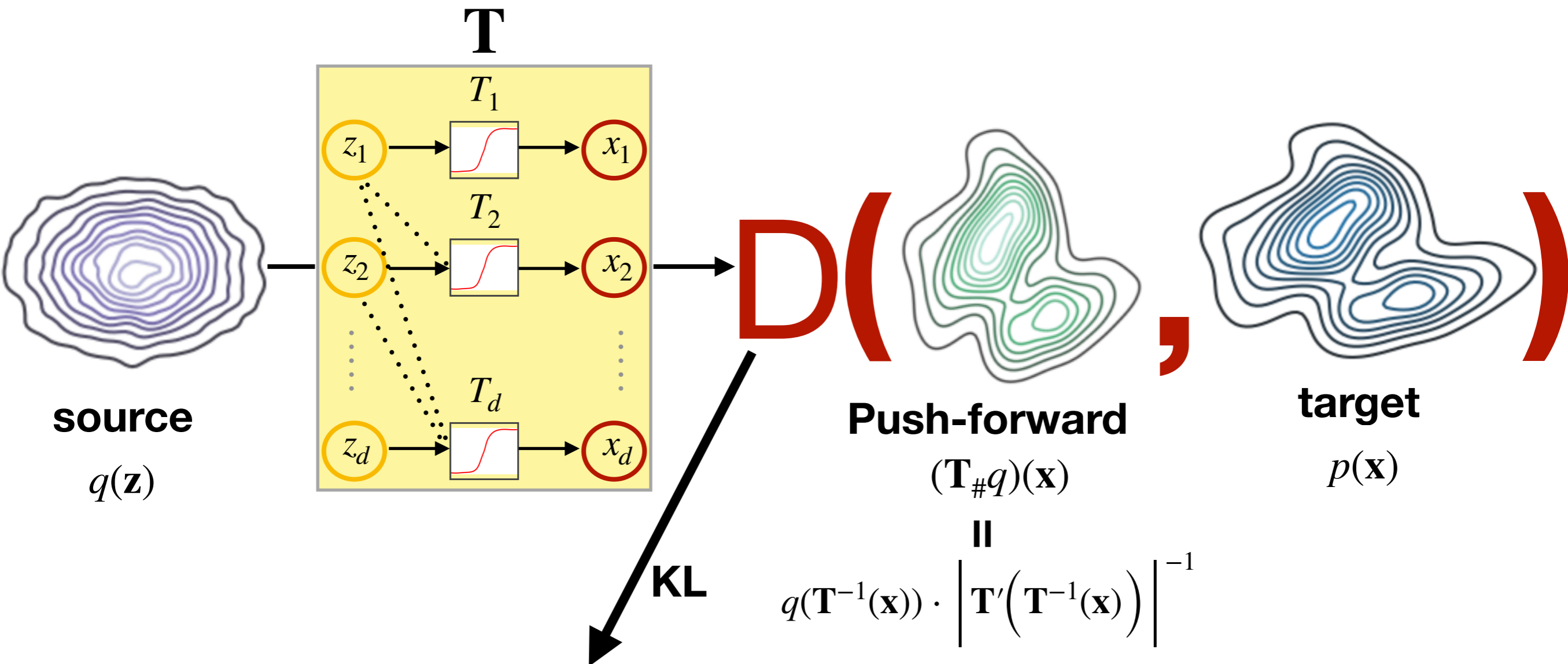
unique increasing triangular $T = \text{chol}(\Sigma)$

Nonlinear Example



Theorem (roughly): there always exists a (unique increasing triangular) map T that pushes any source density to any target density.

Maximum Likelihood revisited



learn T by maximizing likelihood

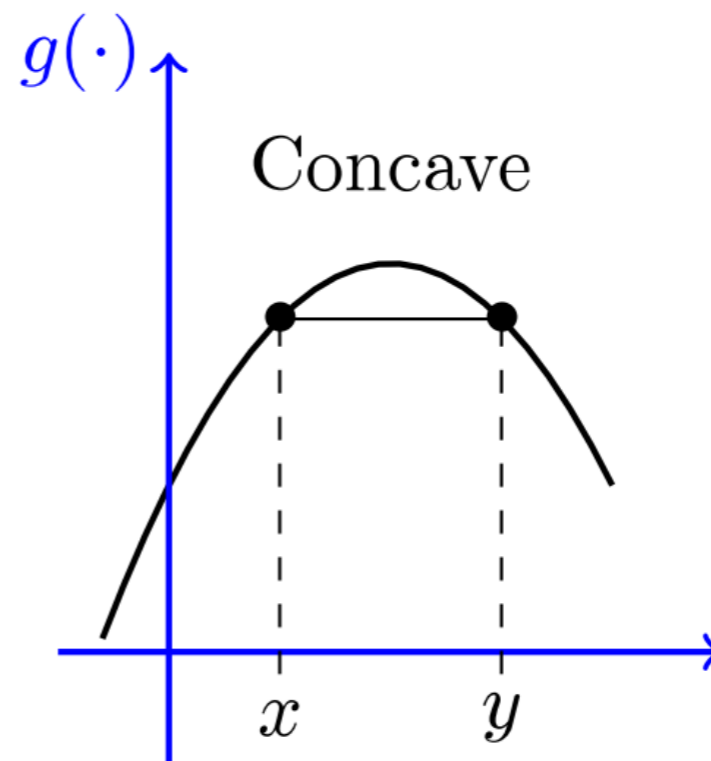
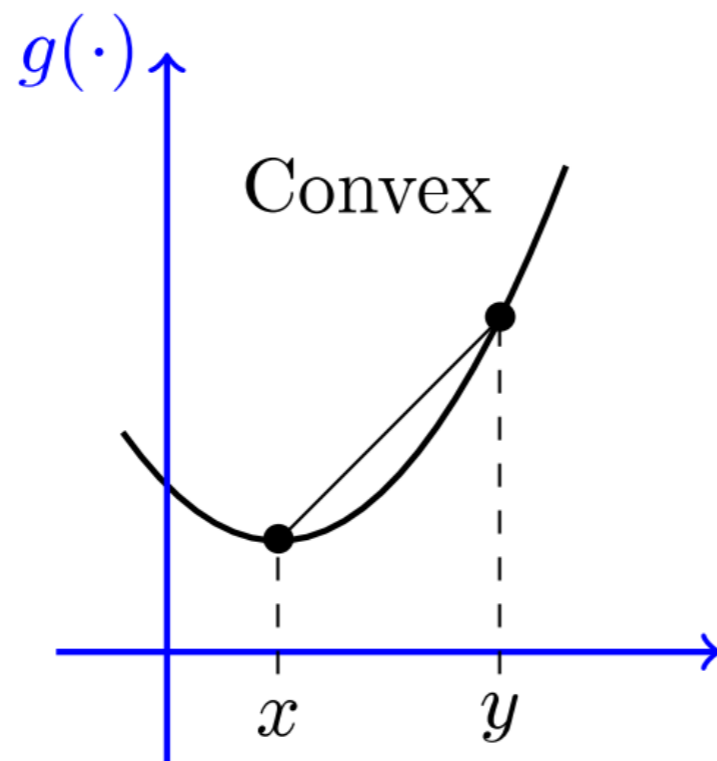
$$\min_{\mathbf{T}} \sum_{i=1}^n \left[-\log q(\mathbf{T}^{-1}(\mathbf{x}_i)) + \sum_j \log \partial_j T_j(\mathbf{T}^{-1}(\mathbf{x}_i)) \right]$$

explicitly evaluating $q_{\theta}(\mathbf{x})$

Another nice tool

Fenchel Conjugate

A univariate real-valued function f is (strictly) convex if $f'' \geq 0$
($>$)



The Fenchel conjugate of f is : $f^*(t) = \max_s st - f(s)$, always convex

Theorem: f is convex iff $f^{**} := (f^*)^* = f$

f-divergence

$$D_f(p||q) := \int f\left(\frac{p(\mathbf{x})}{q(\mathbf{x})}\right) \cdot q(\mathbf{x})d\mathbf{x}$$

where $f : \mathbb{R}_+ \rightarrow \mathbb{R}$ strictly convex and $f(1) = 0$

$$D_f(p||q) \geq f\left(\int \frac{p(\mathbf{x})}{q(\mathbf{x})} \cdot q(\mathbf{x})d\mathbf{x}\right) = f(1) = 0$$

equality **iff** $p = q$

$$D_f(p||q) = \max_{S:\mathbb{R}^d \rightarrow \mathbb{R}} \int S(\mathbf{x}) \cdot p(\mathbf{x})d\mathbf{x} - \int f^*(S(\mathbf{x})) \cdot q(\mathbf{x})d\mathbf{x}$$

$$= \int \max_{S(\mathbf{x})} \left[S(\mathbf{x}) \frac{p(\mathbf{x})}{q(\mathbf{x})} - f^*(S(\mathbf{x})) \right] \cdot q(\mathbf{x})d\mathbf{x}$$

Examples

Kullback–Leibler

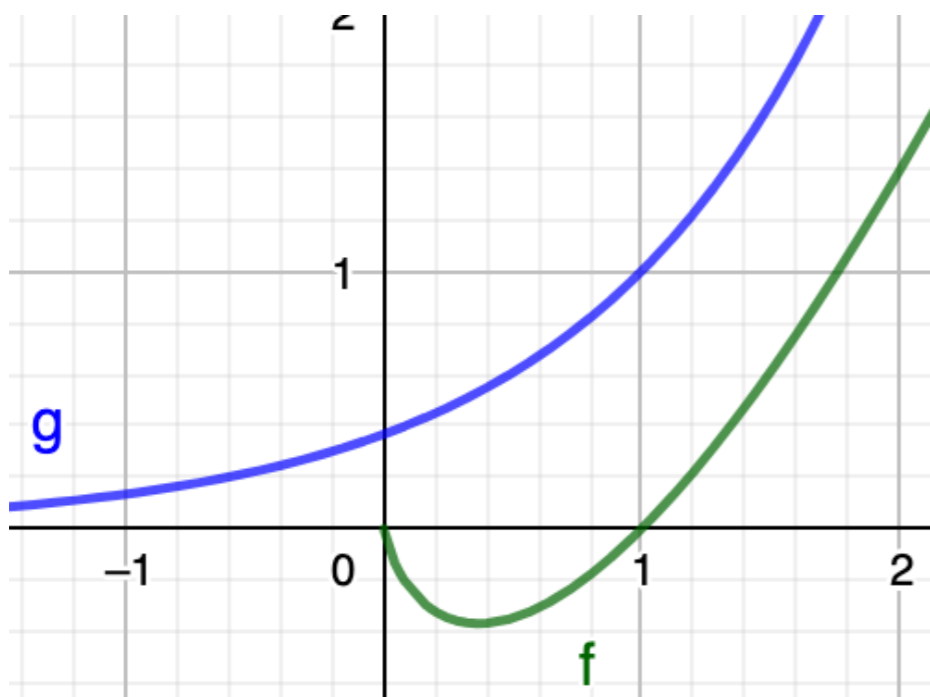
$$f(s) = s \log s$$

$$f''(s) = \frac{1}{s} > 0$$

$$f(1) = 1 \log 1 = 0$$

$$D_f(p\|q) = \int \log \left(\frac{p(\mathbf{x})}{q(\mathbf{x})} \right) \cdot p(\mathbf{x}) d\mathbf{x}$$

$$f^*(t) = \exp(t - 1)$$



Jensen–Shannon

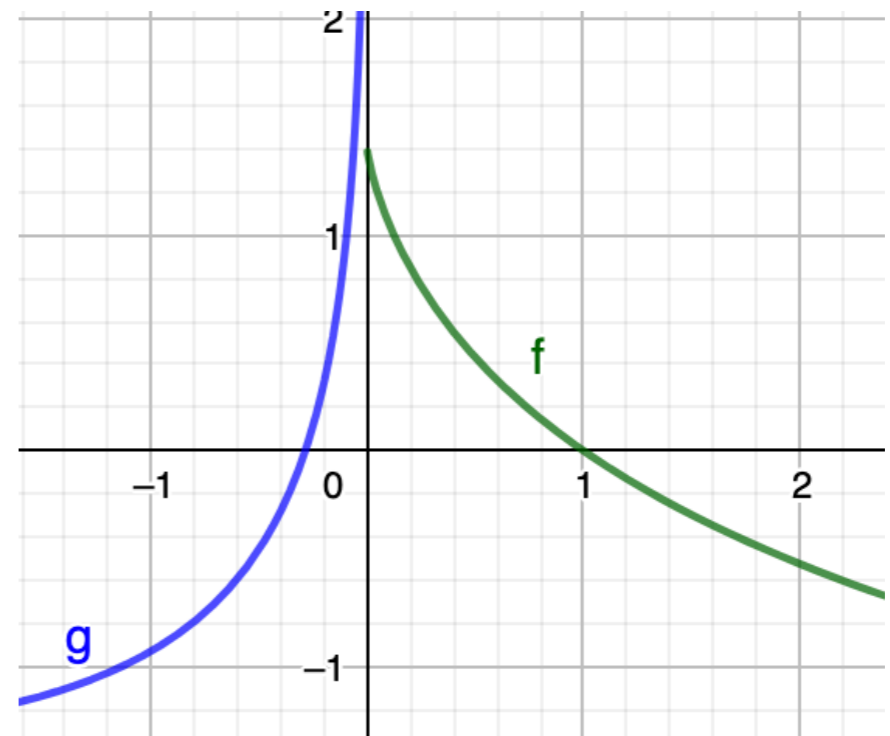
$$f(s) = s \log s - (s + 1) \log(s + 1) + \log 4$$

$$f''(s) = \frac{1}{s} - \frac{1}{s+1} = \frac{1}{s(s+1)} > 0$$

$$f(1) = -2 \log 2 + \log 4 = 0$$

$$D_f(p\|q) = \text{KL}(p\|\frac{p+q}{2}) + \text{KL}(q\|\frac{p+q}{2})$$

$$f^*(t) = -\log(1 - \exp(t)) - \log 4$$



Generative Adversarial Networks (GAN)

Putting things together

$$\min_{\theta} D_f(p(\mathbf{x}) \| q_{\theta}(\mathbf{x})) = \max_{S \in \mathcal{S} \subseteq \mathbb{R}^{\mathbb{R}^d}} \int S(\mathbf{x}) \cdot p(\mathbf{x}) d\mathbf{x} - \int f^*(S(\mathbf{x})) \cdot q_{\theta}(\mathbf{x}) d\mathbf{x}$$

\approx

$$\min_{T_{\theta}} \max_{S_{\varphi}} \frac{1}{n} \sum_{i=1}^n S_{\varphi}(\mathbf{x}_i) - \frac{1}{m} \sum_{j=1}^m f^*(S_{\varphi}(T_{\theta}(\mathbf{z}_j)))$$

generator

discriminator

true sample

generated "fake" sample

$$\tilde{\mathbf{x}} = T_{\theta}(\mathbf{z})$$

both parameterized as DNN

sampling
explicitly evaluating $q_{\theta}(\mathbf{x})$

Example: JS-GAN

$$\min_{T_\theta} \max_{S_\varphi} \frac{1}{n} \sum_{i=1}^n S_\varphi(\mathbf{x}_i) - \frac{1}{m} \sum_{j=1}^m f^*(S_\varphi(T_\theta(\mathbf{z}_j)))$$

$$D_f(p \| q) = \text{KL}(p \| \frac{p+q}{2}) + \text{KL}(q \| \frac{p+q}{2})$$

$$f^*(t) = -\log(1 - \exp(t)) - \log 4 \quad t \leq 0$$



$$S \leftarrow \log S$$

$$\min_{T_\theta} \max_{S_\varphi} \frac{1}{n} \sum_{i=1}^n \log S_\varphi(\mathbf{x}_i) + \frac{1}{m} \sum_{j=1}^m \log(1 - S_\varphi(T_\theta(\mathbf{z}_j)))$$

$$0 \leq S_\varphi \leq 1$$

sampling
explicitly evaluating $q_\theta(\mathbf{x})$

Interpreting JS-GAN

Generator tries to “fool” discriminator

$$\min_{T_\theta} \max_{S_\varphi} \frac{1}{n} \sum_{i=1}^n \log S_\varphi(\mathbf{x}_i) + \frac{1}{m} \sum_{j=1}^m \log(1 - S_\varphi(T_\theta(\mathbf{z}_j))) \quad 0 \leq S_\varphi \leq 1$$

Discriminator performs nonlinear logistic regression, where $p = S_\varphi$

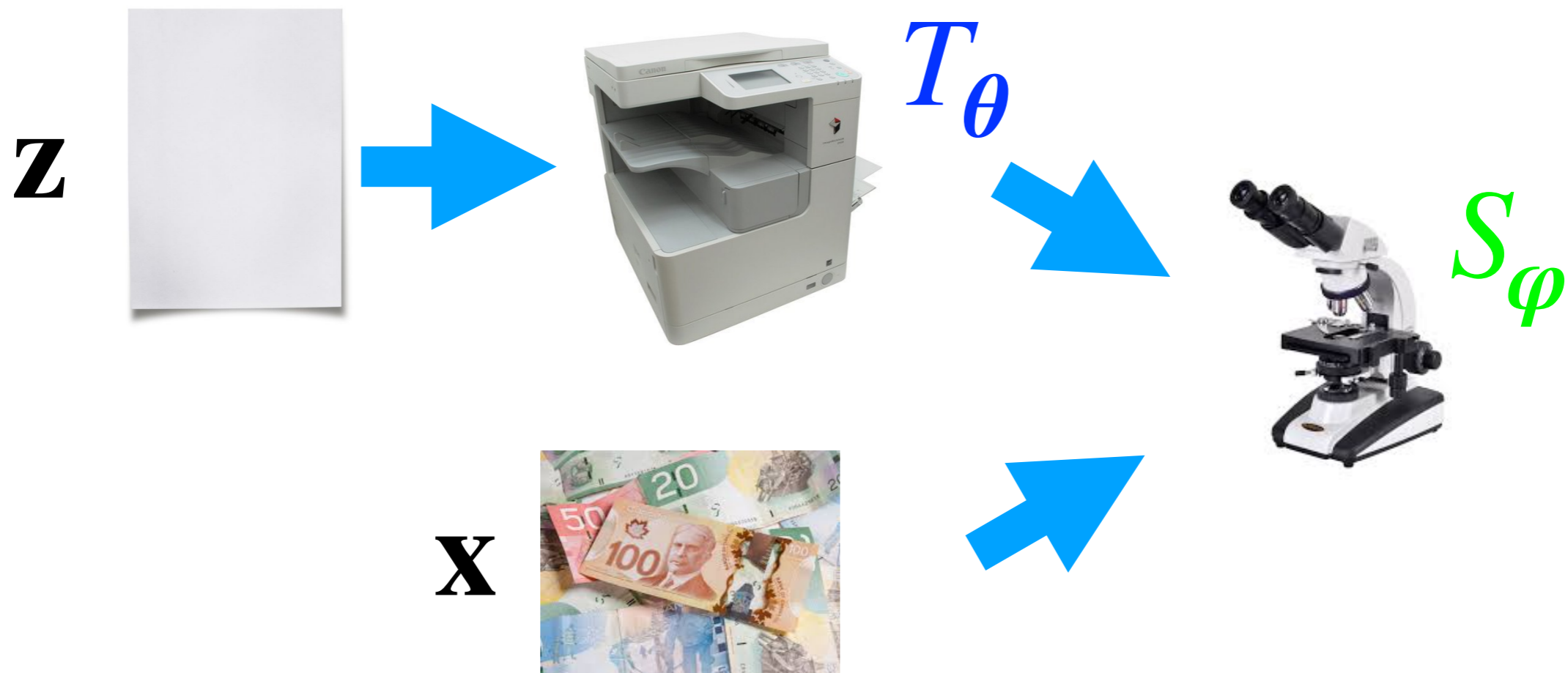
$$y = \begin{cases} 1, & \text{true sample} \\ -1, & \text{generated "fake" sample} \end{cases}$$

Two-player zero-sum game: at equilibrium true sample = generated “fake” sample

sampling
explicitly evaluating $q_\theta(\mathbf{x})$

Interpreting JS-GAN

$$\min_{T_\theta} \max_{S_\varphi} \frac{1}{n} \sum_{i=1}^n \log S_\varphi(\mathbf{x}_i) + \frac{1}{m} \sum_{j=1}^m \log(1 - S_\varphi(T_\theta(\mathbf{z}_j)))$$



Two-player zero-sum game: at equilibrium true sample = generated “fake” sample

After training

$$\min_{T_\theta} \max_{S_\varphi} \frac{1}{n} \sum_{i=1}^n \log S_\varphi(\mathbf{x}_i) + \frac{1}{m} \sum_{j=1}^m \log(1 - S_\varphi(T_\theta(\mathbf{z}_j)))$$



Two-player zero-sum game: at equilibrium true sample = generated "fake" sample

Strong/Weak duality

$$\min_{T_\theta} \max_{S_\varphi} \frac{1}{n} \sum_{i=1}^n \log S_\varphi(\mathbf{x}_i) + \frac{1}{m} \sum_{j=1}^m \log(1 - S_\varphi(T_\theta(\mathbf{z}_j))) \quad 0 \leq S_\varphi \leq 1$$

$\rightsquigarrow n, m \rightarrow \infty$ arbitrary T_θ, S_φ

$$\max_{S_\varphi} \min_{T_\theta} \frac{1}{n} \sum_{i=1}^n \log S_\varphi(\mathbf{x}_i) + \frac{1}{m} \sum_{j=1}^m \log(1 - S_\varphi(T_\theta(\mathbf{z}_j)))$$

Two-player zero-sum game: at equilibrium true sample = generated “fake” sample

sampling
explicitly evaluating $q_\theta(\mathbf{x})$

More GANs through IPM

$$\min_{T_\theta} \max_{S_\varphi} \frac{1}{n} \sum_{i=1}^n S_\varphi(\mathbf{x}_i) - \frac{1}{m} \sum_{j=1}^m S_\varphi(T_\theta(\mathbf{z}_j))$$

- **S** is the class of Lipschitz continuous functions: Wasserstein GAN
- **S** is the unit ball of some RKHS: MMD-GAN
- **S** is the class of indicator functions: TV-GAN
- **S** is the unit ball of some Sobolev space: Sobolev-GAN
- **S** is the class of differential functions: Stein-GAN
-
-

Two-player zero-sum game: at equilibrium true sample = generated “fake” sample

sampling
explicitly evaluating $q_\theta(\mathbf{x})$

The GAN Zoo

Cumulative number of named GAN papers by month

