



CS480/680: Intro to ML

Lecture 05: K -nearest neighbors

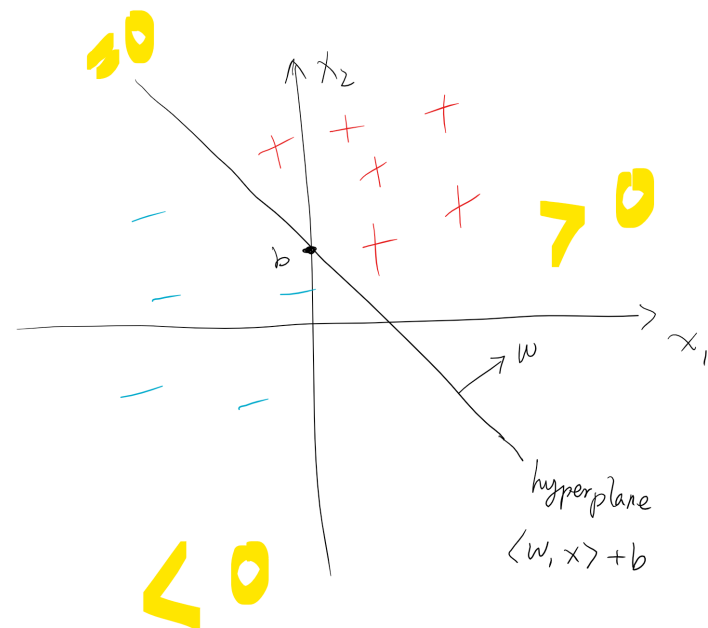


Outline

- Algorithm
- Theory
- Application

Classification revisited

- $\hat{y} = \text{sign}(\mathbf{x}^T \mathbf{w} + b)$
- Decision boundary: $\mathbf{x}^T \mathbf{w} + b = 0$
- Parametric: finite-dim $\mathbf{w}$
- Non-parametric: no specific form (or inf-dim $\mathbf{w}$)



1-Nearest Neighbour

- Store training set $(X, \mathbf{y})$
- For query (test point) $\mathbf{x}'$
 - find nearest point $\mathbf{x}$ in X
 - predict $y' = y(\mathbf{x})$

What do you mean “nearest”

- Need to measure distance or similarity
- $d: X \times X \rightarrow \mathbb{R}_+$ such that
 - **symmetry**: $d(x, x') = d(x', x)$
 - **definite**: $d(x, x') = 0$ iff $x = x'$
 - **triangle inequality**: $d(a, b) \leq d(a, c) + d(c, b)$

L_p distance: $d_p(x, x') = \|x - x'\|_p$

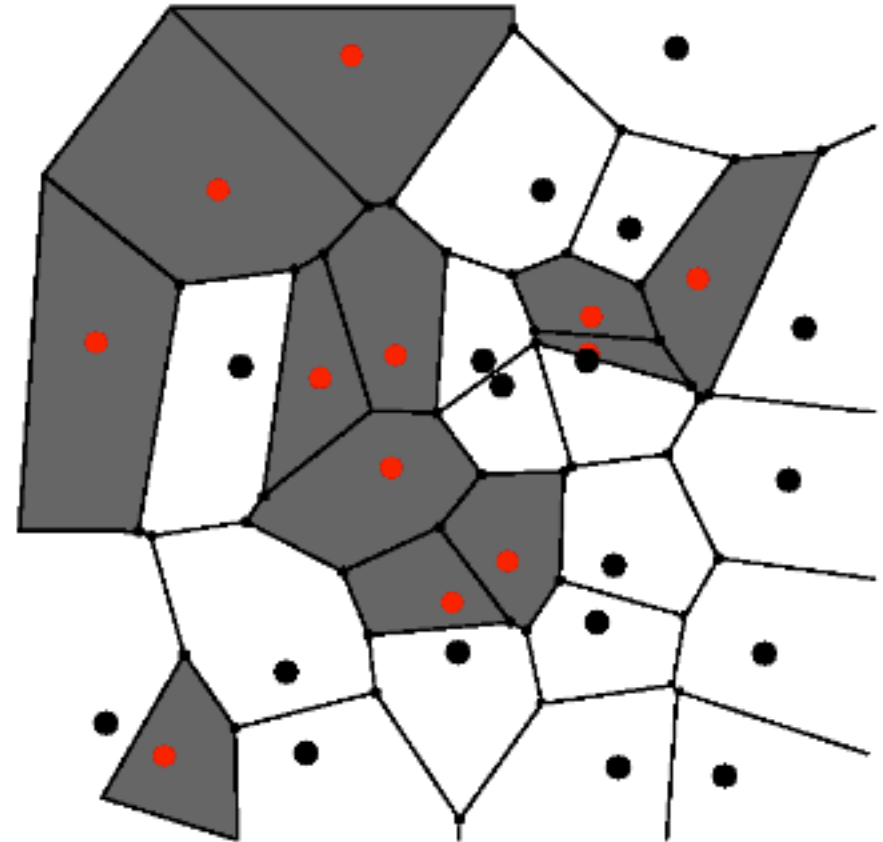
- $p=2$: Euclidean distance
- $p=1$: Manhattan distance
- $p=\infty$: Chebyshev distance

Complexity of 1-NN

- Training: **0...** but $O(nd)$ space
- Testing: $O(nd)$ for each query point
 - n : # of training samples
 - d : # of features
- Can we do better?

Voronoi diagram

- In 2D, can construct in $O(n \log n)$ time and $O(n)$ space (Fortune, 1989)
- In 2D, query costs $O(\log n)$
- Large d ? $n^{O(d)}$ space with $O(d \log n)$ query time 😞
 - approximate NN

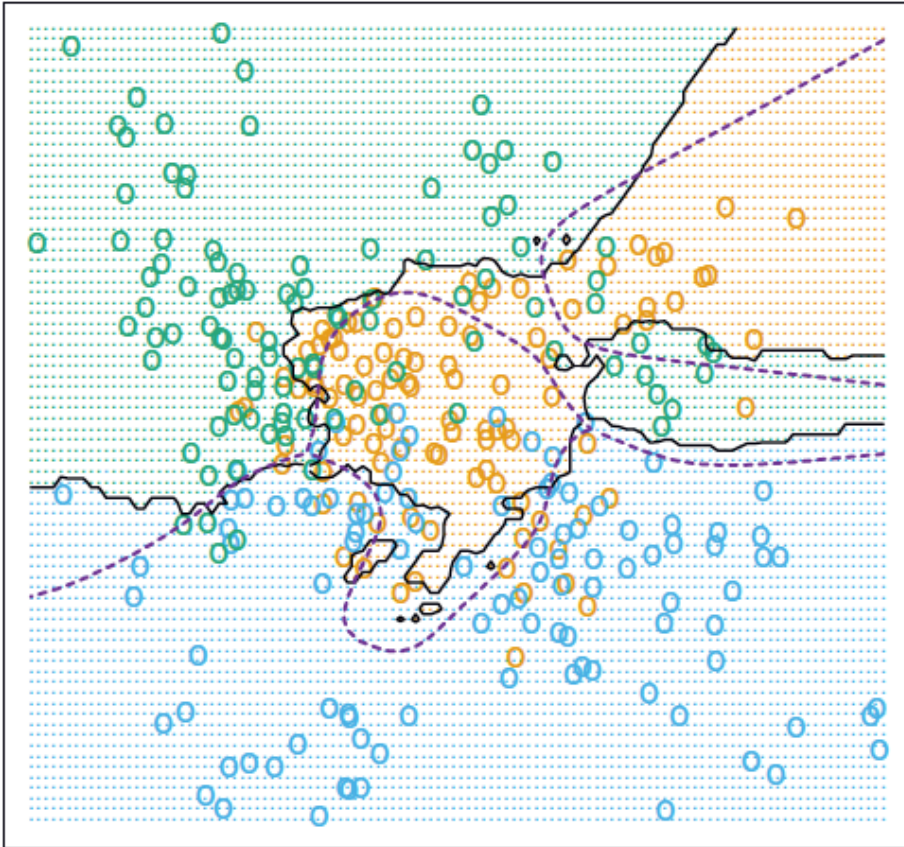


k-NN

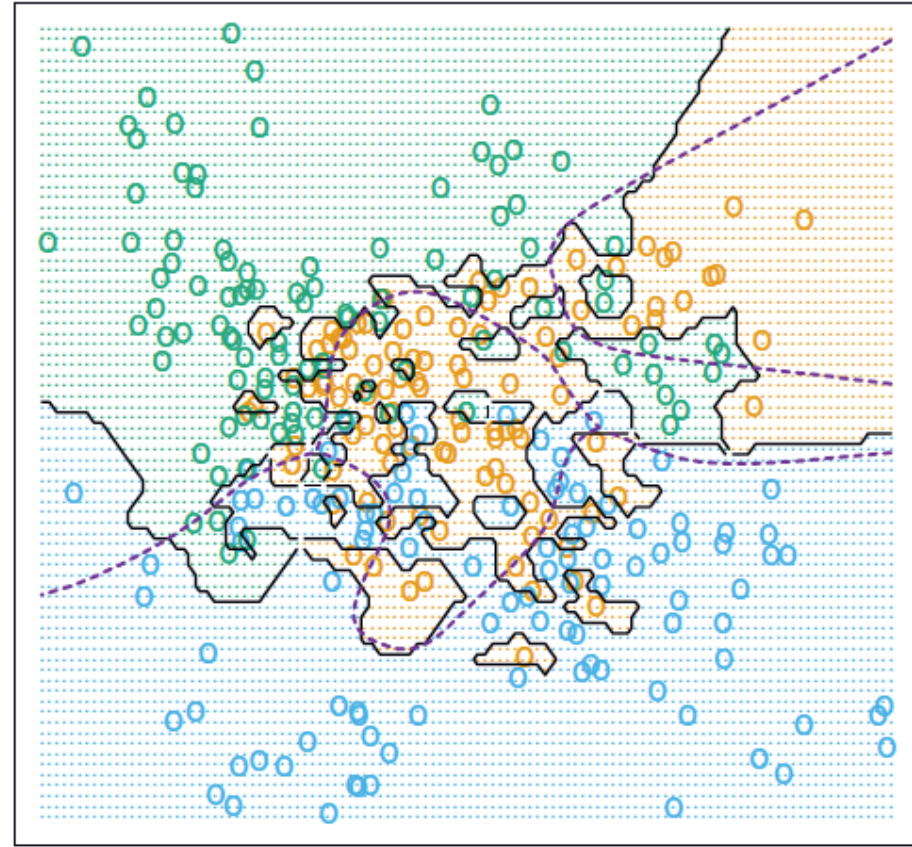
- Store training set $(X, \mathbf{y})$
- For query (test point) $\mathbf{x}'$
 - find k nearest points $\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_k$ in X
 - predict $y' = y(\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_k)$
 - usually a majority vote among the labels of $\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_k$
 - say $y_1=1, y_2=1, y_3=-1, y_4=1, y_5=-1 \rightarrow y' =$
- Test complexity: $O(nd)$

Effect of k

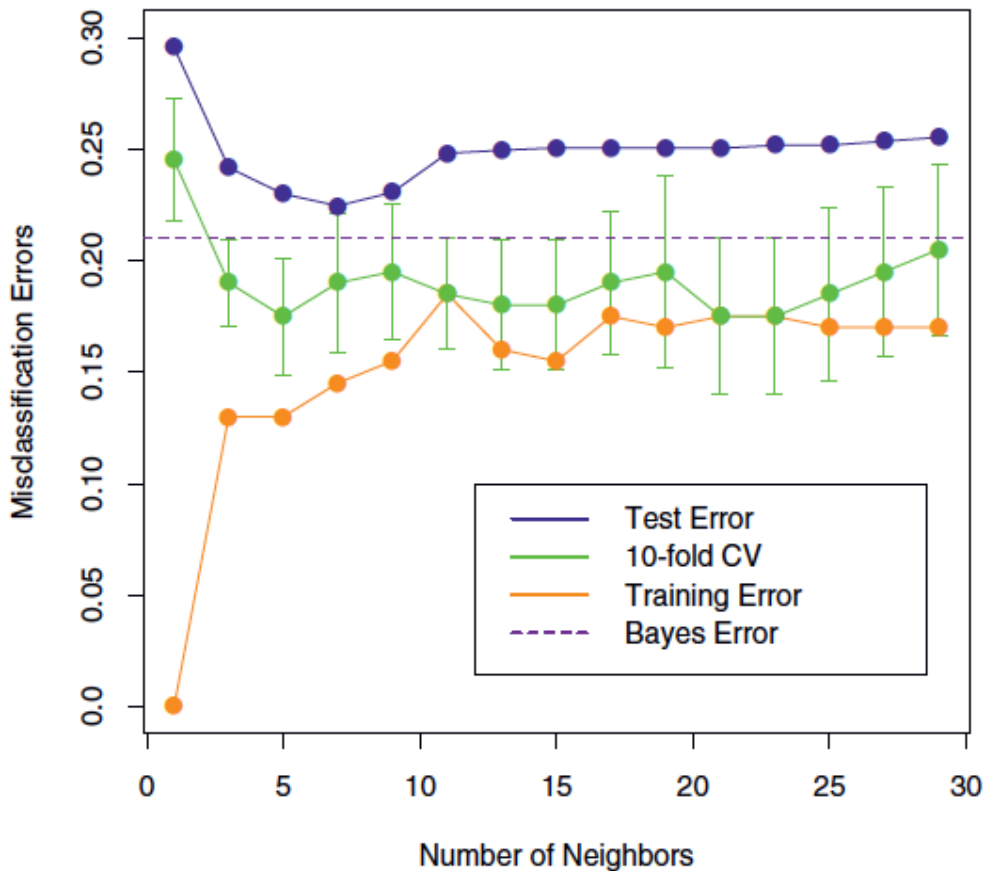
15-Nearest Neighbors



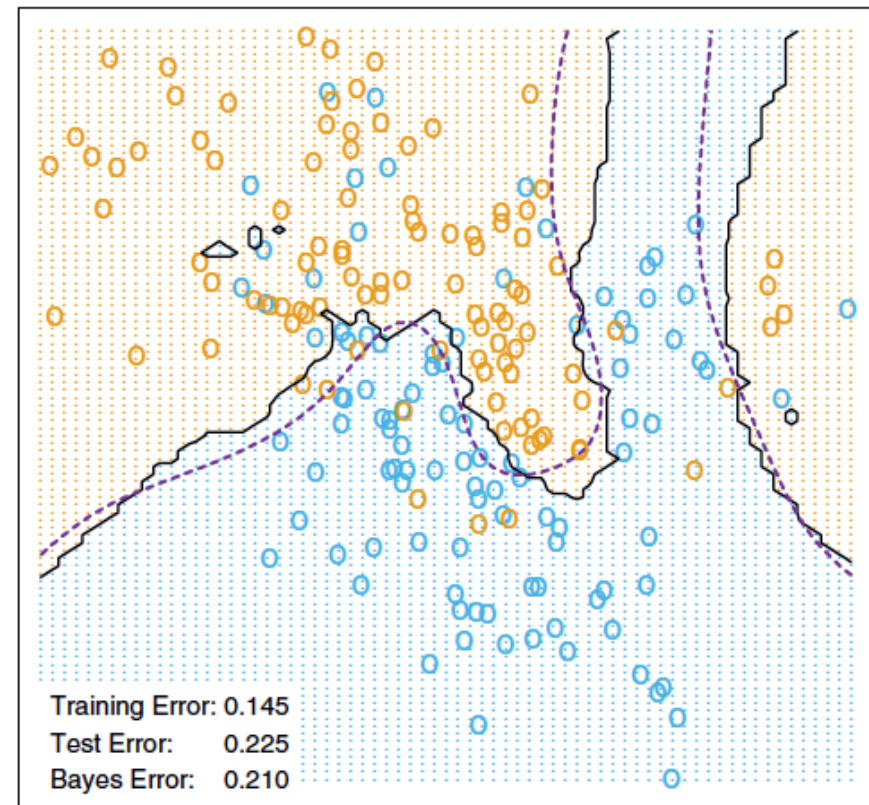
1-Nearest Neighbor



How to select k?

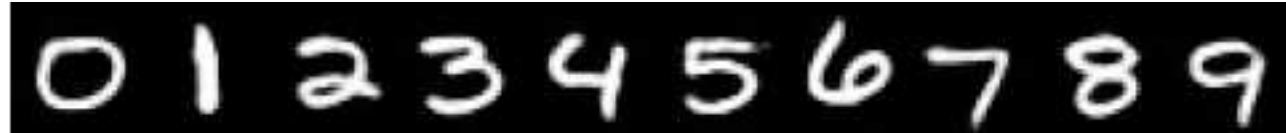


7-Nearest Neighbors



Does k-NN work?

MNIST: 60k train, 10k test



linear classifier (1-layer NN)	none	12.0	LeCun et al. 1998
2-layer NN, 300 hidden units, mean square error	none	4.7	LeCun et al. 1998
6-layer NN 784-2500-2000-1500-1000-500-10 (on GPU) [elastic distortions]	none	0.35	Ciresan et al. Neural Computation 10, 2010 and arXiv 1003.0358, 2010
SVM, Gaussian Kernel	none	1.4	
Virtual SVM, deg-9 poly, 2-pixel jittered	deskewing	0.56	DeCoste and Scholkopf, MLJ 2002
Convolutional net LeNet-4	none	1.1	LeCun et al. 1998
committee of 35 conv. net, 1-20-P-40-P-150-10 [elastic distortions]	width normalization	0.23	Ciresan et al. CVPR 2012
K-nearest-neighbors, Euclidean (L2)	none	3.09	Kenneth Wilder, U. Chicago
K-nearest-neighbors, L3	none	2.83	Kenneth Wilder, U. Chicago
K-NN with non-linear deformation (P2DHMDM)	shiftable edges	0.52	Keysers et al. IEEE PAMI 2007

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Bayes rule

- Bayes error $P^* = \min_{f: \mathcal{X} \rightarrow \{\pm 1\}} \mathbf{P}(f(X) \neq Y)$
- Bayes rule

$$\eta(X) = \mathbf{P}(Y = 1|X)$$

$$f^*(X) = 1 \text{ iff } \eta(X) \geq \frac{1}{2}$$

Multi-class

$$f^*(X) = \operatorname{argmax}_{m=1,\dots,c} P(Y = m|X)$$

$$P^* = \mathbf{E}\left[1 - \max_{m=1,\dots,c} P(Y = m|X)\right]$$

- This is the **best** we can do **even when we know the distribution of (X,Y)**
- How big can P^* be?

At most twice worse (Cover & Hart'67)

$$\lim_{n \rightarrow \infty} P(Y_1^{(n)} \neq Y) \leq 2P^* - c/(c-1) (P^*)^2$$

Asymptotically!

1-NN error

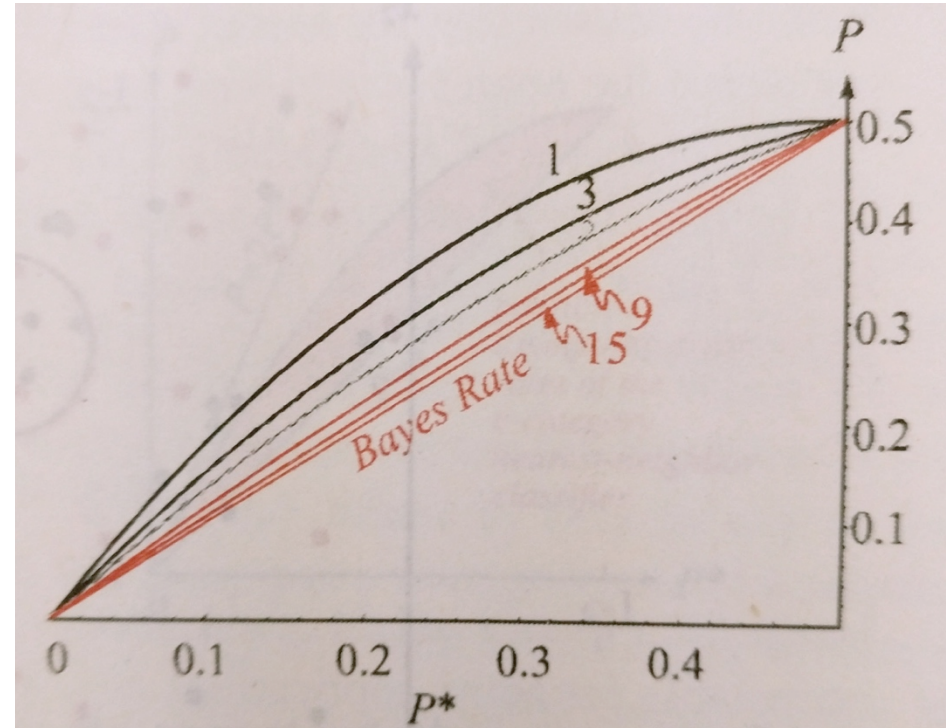
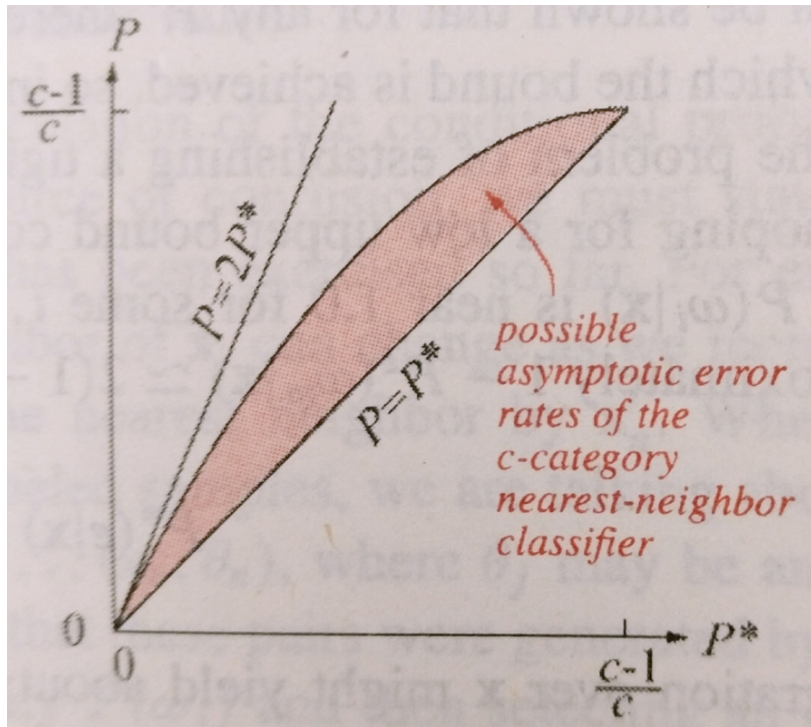
Bayes error

of classes

$1 / (\max P^*)$

- If P^* close to 0, then 1-NN error close to $2P^*$
- How big does n have to be?

The picture



Both assume we have infinite amount of training data!

1-NN vs k-NN

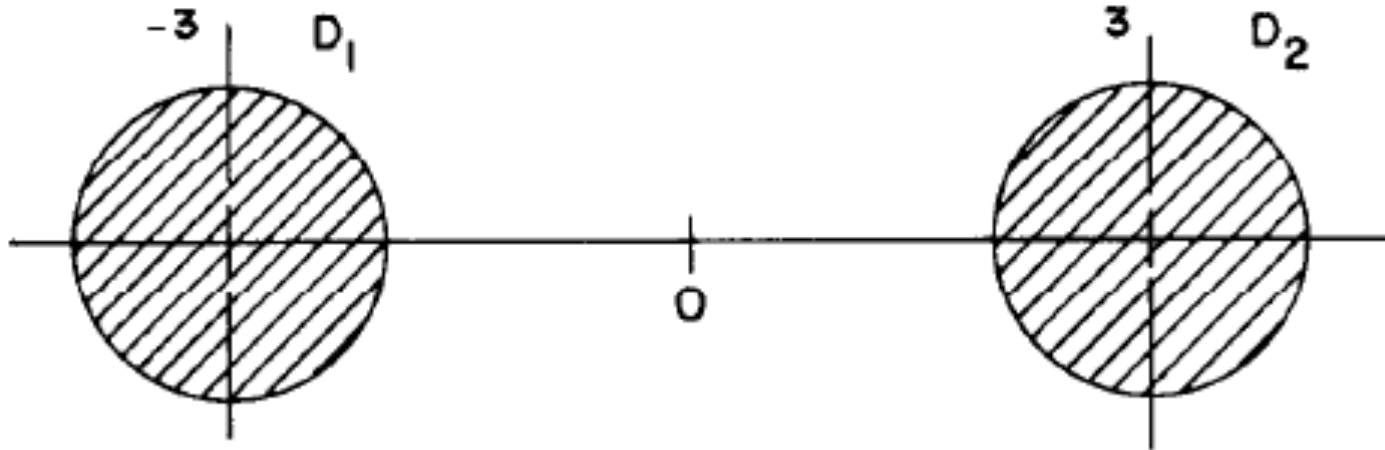


Fig. 1. Admissibility of nearest neighbor rule.

- $\text{error}(1\text{NN}) = 1/2^n$
- $\text{error}(k\text{NN})$ for $k = 2t+1$: $\frac{1}{2^n} \sum_{i=0}^t \binom{n}{i}$

Curse of dimensionality

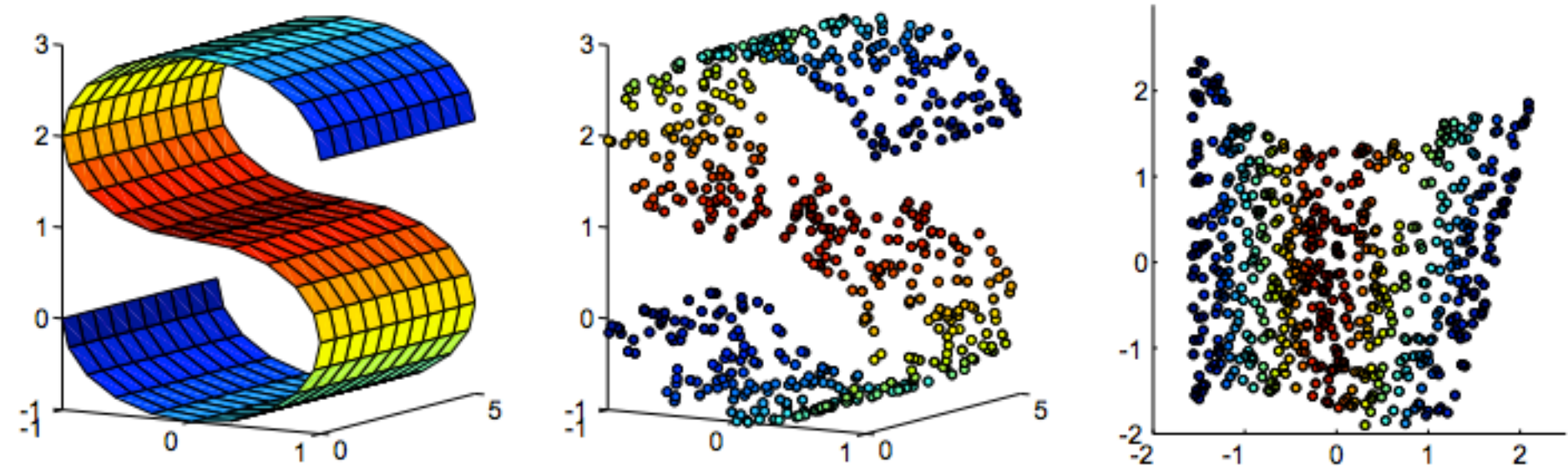
Theorem (SSBD, p224). For any $c > 1$ and **any** learning algorithm L , there exists a distribution over $[0, 1]^d \times \{0, 1\}$ such that the Bayes error is 0 but for sample size $n \leq (c+1)^{d/2}$, the error of the rule L is greater than $1/4$.

- k-NN is effective when have **many** training samples
- Dimensionality reduction may be helpful

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Locally linear embedding (Saul & Roweis'00)

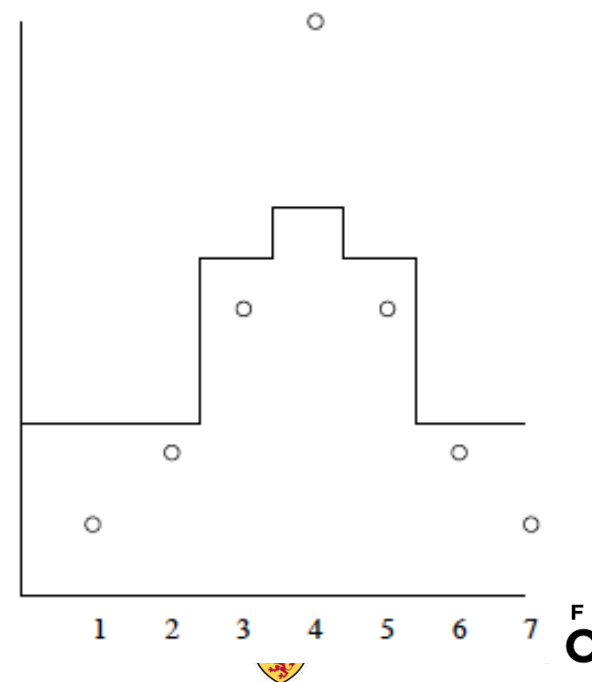
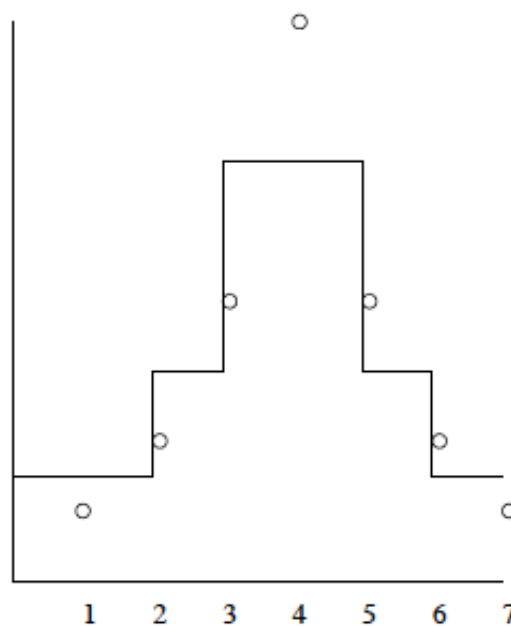
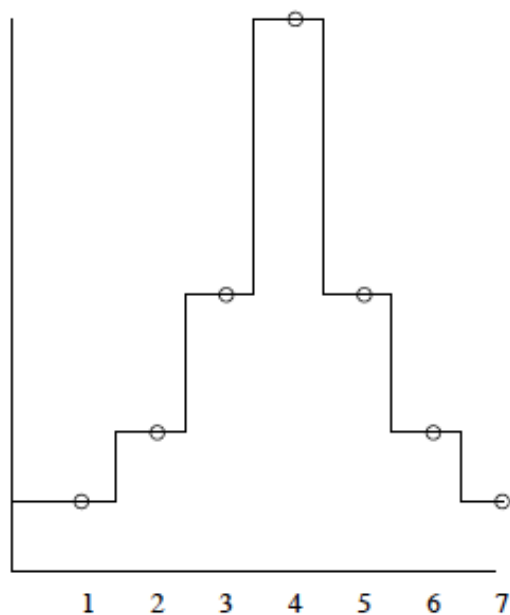


$$\min_{W_{1=1}} \left\| \mathbf{x}_i - \sum_j W_{ij} \mathbf{x}_j \right\|_2^2$$

$$\min_Z \sum_i \left\| \mathbf{z}_i - \sum_j W_{ij} \mathbf{z}_j \right\|_2^2$$

k-NN for regression

- Training: store training set (X, y)
- Query x'
 - Find k-nns $\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_k$ in X
 - output $y' = y(\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_k) = (y_1 + y_2 + \dots + y_k)/k$



Questions?

